

Learning Treatment Policies from Observational Data



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MIT

Overview

Goals

- By the end of this primer, you should understand...
 - What a **causal effect** is, and when we can infer it from observational data
“What is the effect of treatment vs. placebo?”
 - How **causal effect estimation** is a special case of **policy evaluation**
“What would happen if I implemented a new set of guidelines?”
 - How to use policy evaluation to **learn optimal policies**
“What is the optimal treatment strategy?”

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Causal Effects

(and related quantities, like the Average Treatment Effect)

What is a causal effect?

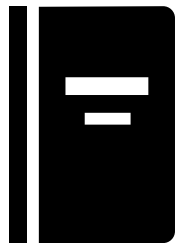
- What is the effect of...
 - Thiazide on cardiac outcomes in hypertensive patients? [1]
 - Hydroxychloroquine on adverse events in COVID-19 patients? [2]
 - ...
- Causal questions from large observational datasets

[1] M. A. Suchard et al., "Comprehensive comparative effectiveness and safety of first-line antihypertensive drug classes : a systematic , multinational, large-scale analysis," Lancet, vol. 6736, no. 19, pp. 1–11, 2019.

[2] J. C. E. Lane et al., "Safety of hydroxychloroquine, alone and in combination with azithromycin, in light of rapid wide-spread use for COVID-19: a multinational, network cohort and self-controlled case series study," medRxiv, 2020.

Conclusions of an Observational Study

THE LANCET

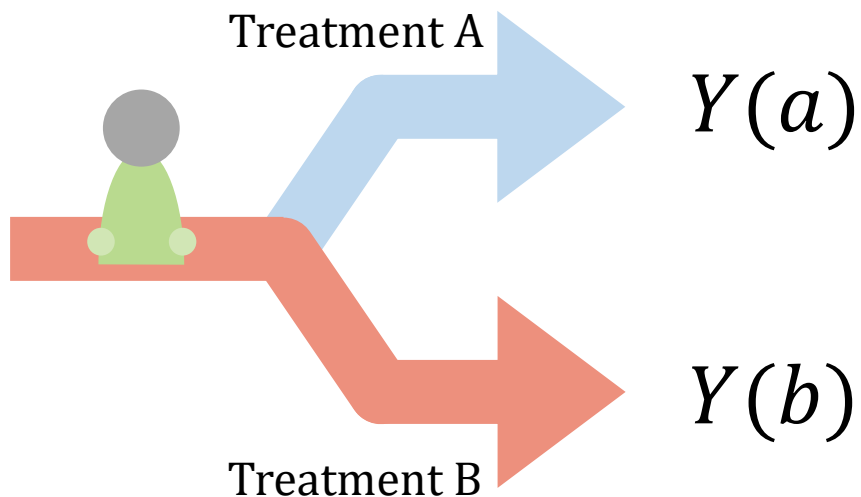


“thiazide [...] showed better primary effectiveness than [ACE] inhibitors” [1]

[1] M. A. Suchard et al., “Comprehensive comparative effectiveness and safety of first-line antihypertensive drug classes : a systematic , multinational, large-scale analysis,” Lancet, vol. 6736, no. 19, pp. 1–11, 2019.

“What is the effect” as a causal question

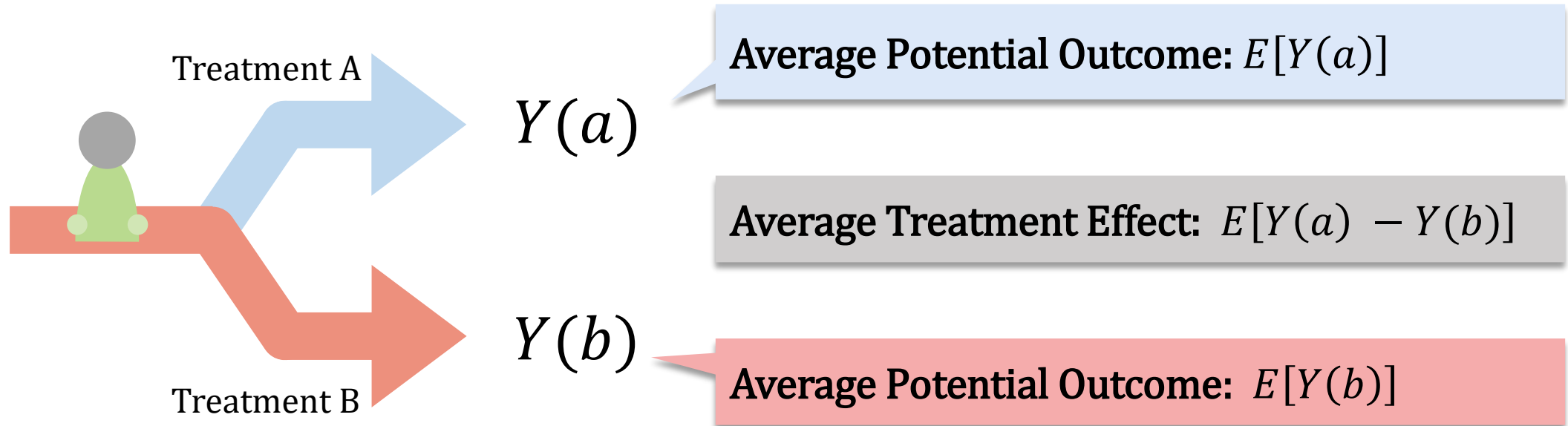
Every patient has a set of potential outcomes $Y(t)$, corresponding to different treatment decisions t .



Average Treatment Effect: $E[Y(a) - Y(b)]$

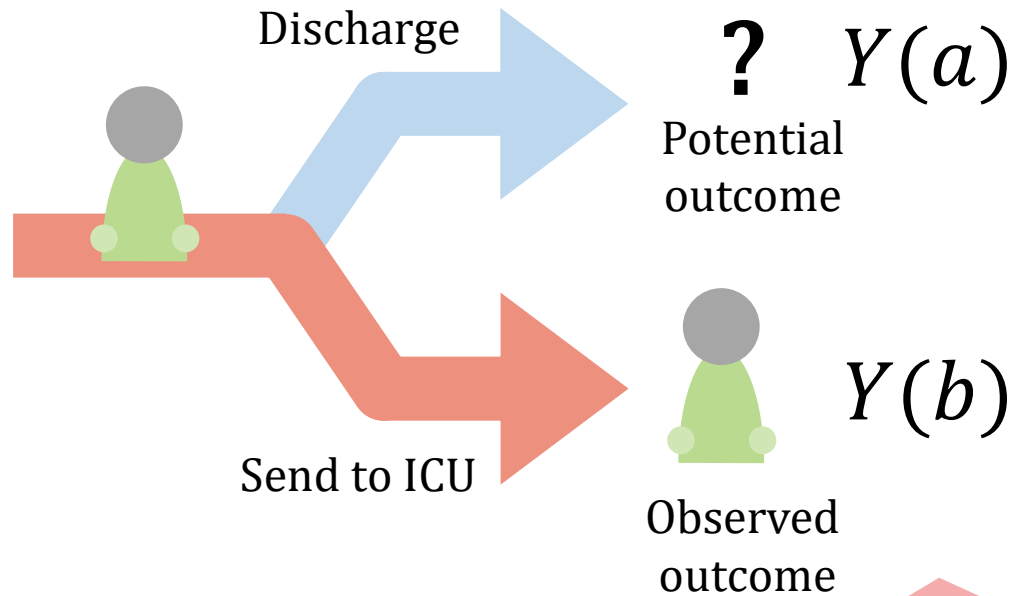
“What is the effect” as a causal question

Every patient has a set of potential outcomes $Y(t)$, corresponding to different treatment decisions t .



I will refer to all these quantities as “causal effects”, though that is more commonly used to refer to a contrast like the Average Treatment Effect

The challenge: We don't observe all outcomes!



Illustrative Example

- Suppose COVID-19 patients who are sent to the ICU have higher mortality rates
- Should we stop sending patients to the ICU?

Challenge: $E[Y(b)] \neq E[Y \mid T = b]$

Correlation does not imply causation

Correlation ~~does not~~ imply causation

Carefully chosen correlation can imply causation

(under some untestable assumptions)

From Correlation to Causation

1

Consistency

When treatment t is given, we observe $Y(t)$

2

No interference

Your outcome is not impacted by the treatments of others

3

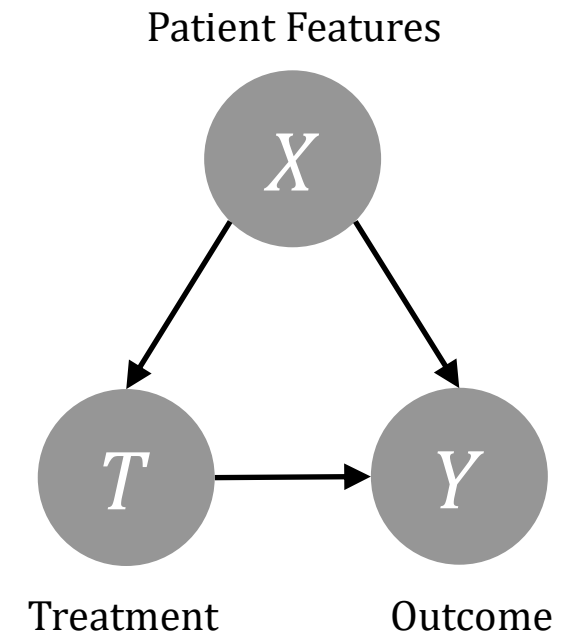
No unmeasured confounding

We have measured all relevant confounders

4

Overlap / Coverage

All types of patients receive all treatments*



*More on this later, when we discuss policy evaluation

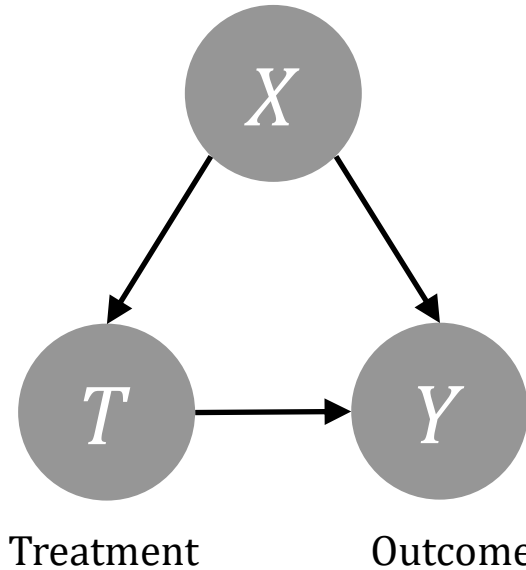
From Correlation to Causation

Causal Query

$$E[Y(t)]$$

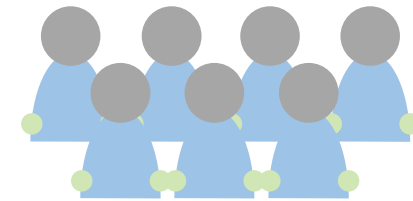
Causal
Assumptions

Patient Features



Statistical Query

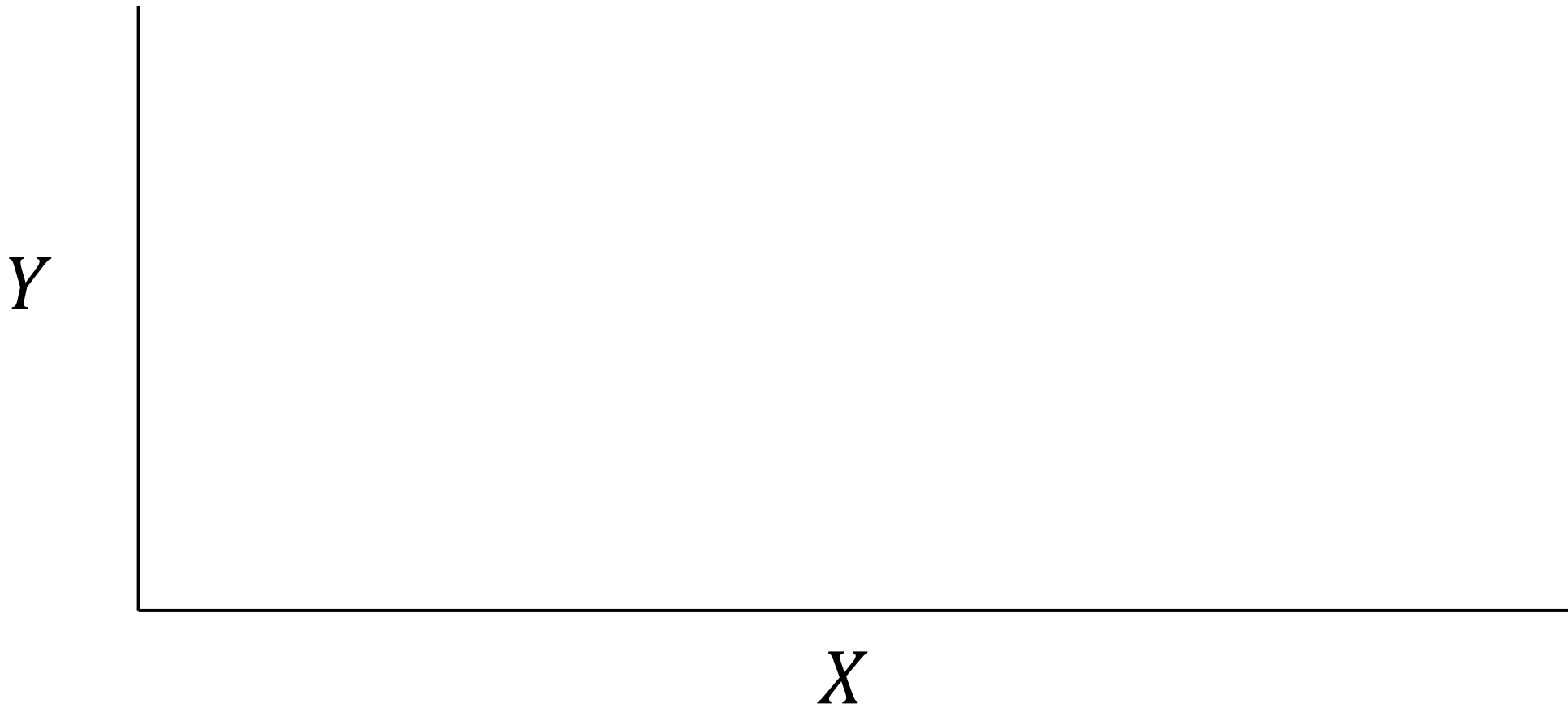
$$E[E[Y | X, T = t]]$$



Observational Data

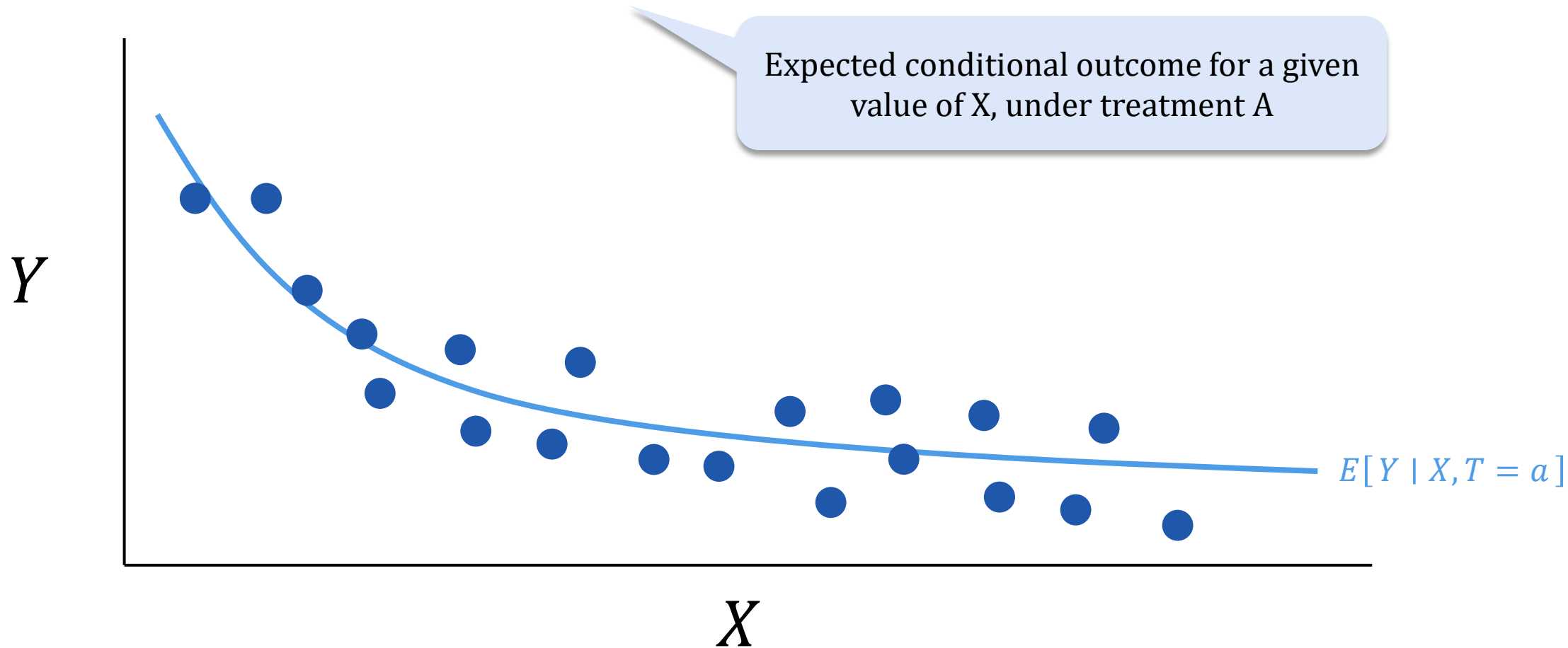
Average Potential Outcomes

$$E[Y(a)] = E_x[E[Y \mid X, T = a]]$$



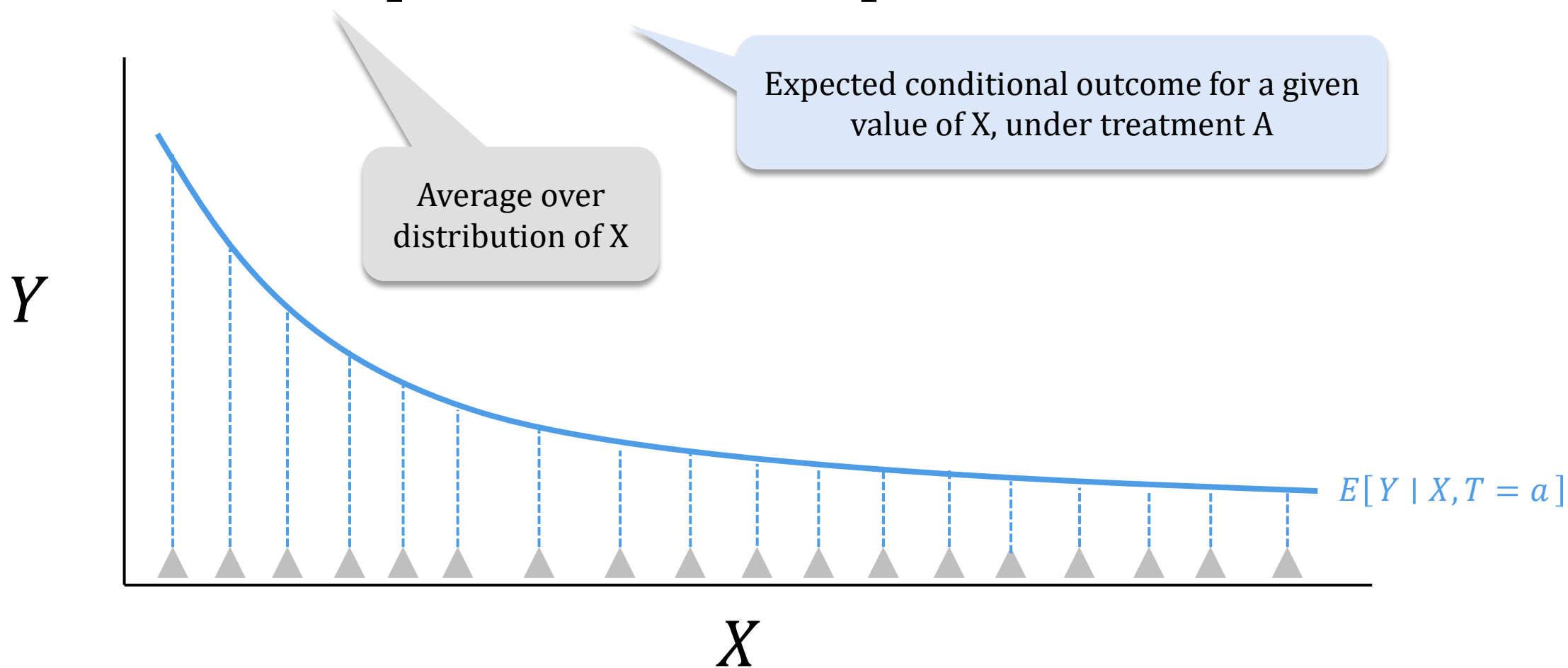
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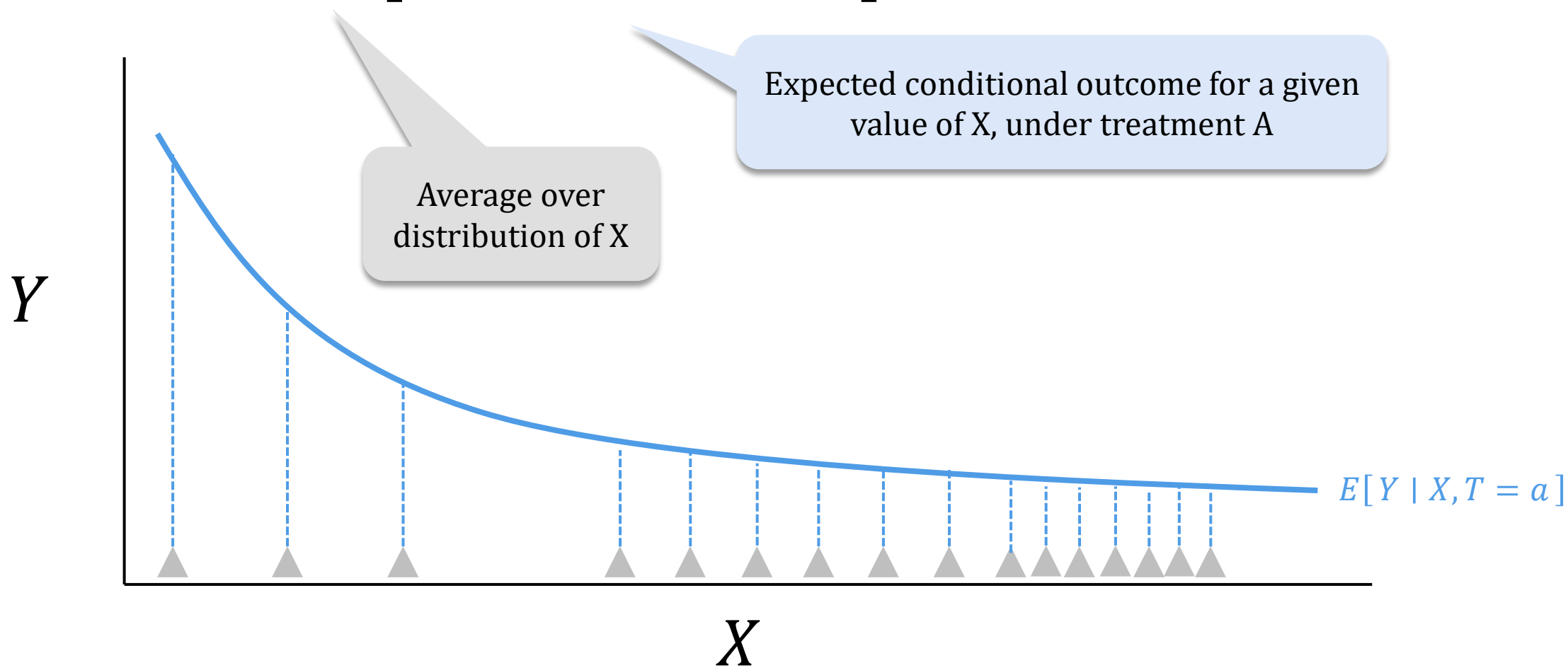
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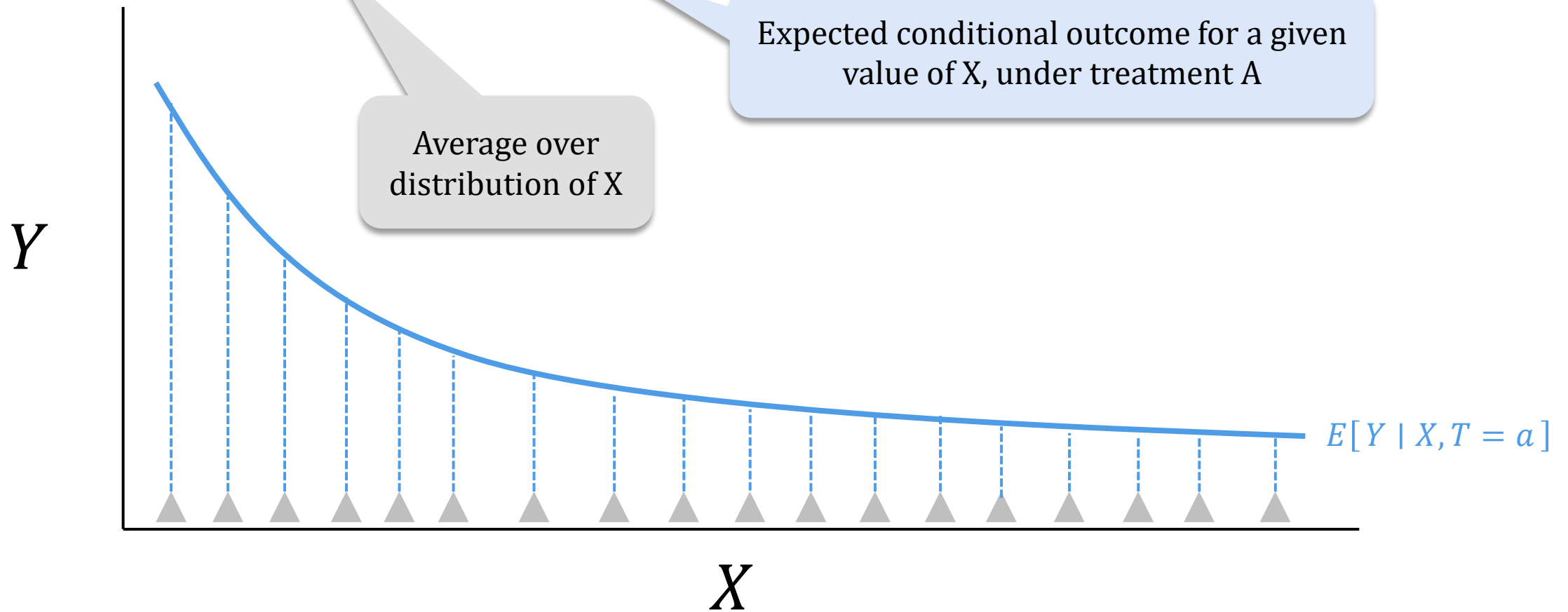
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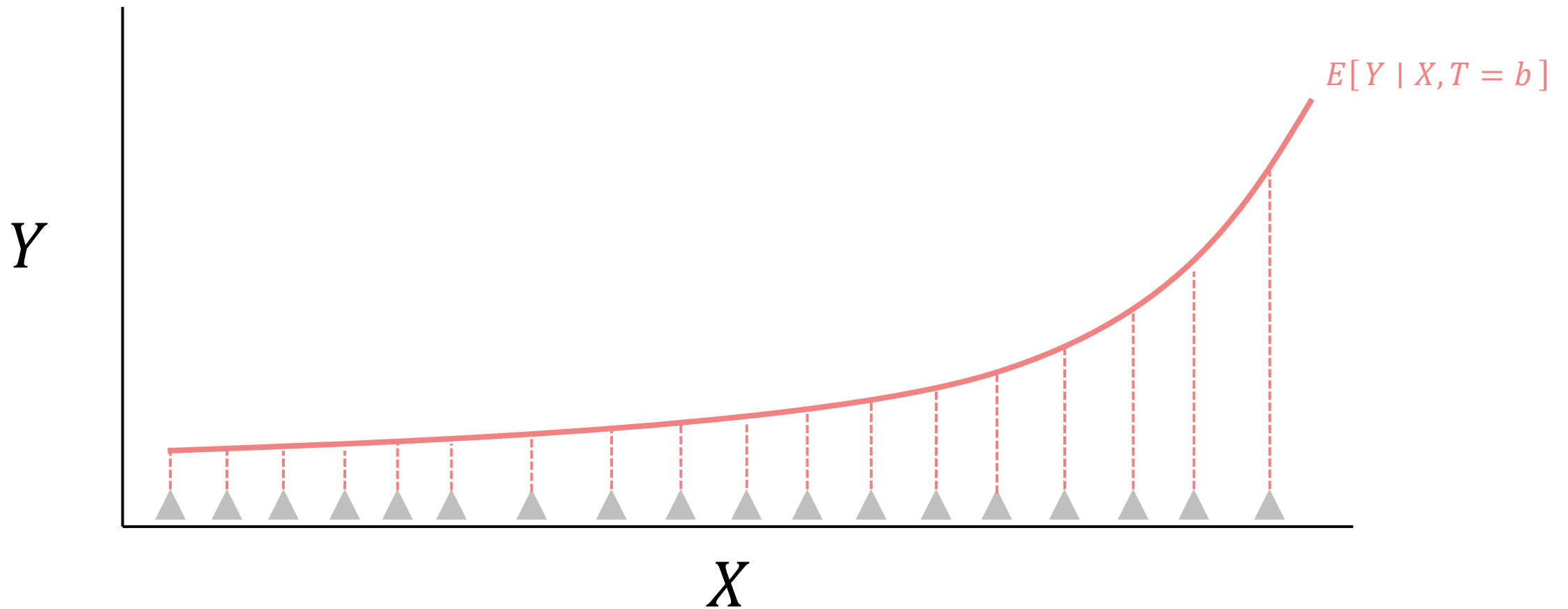
Average Potential Outcomes

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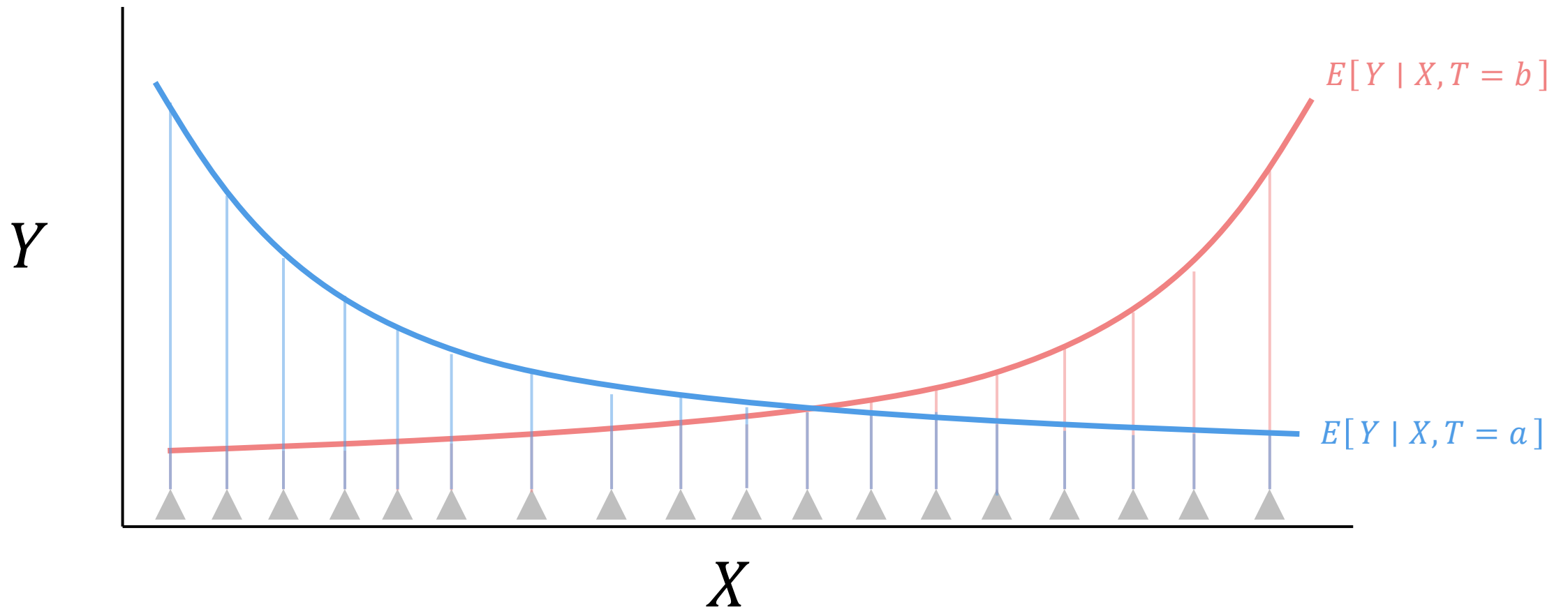


What about a different treatment?

$$E[Y(b)] = E_x[E[Y \mid X, T = b]]$$

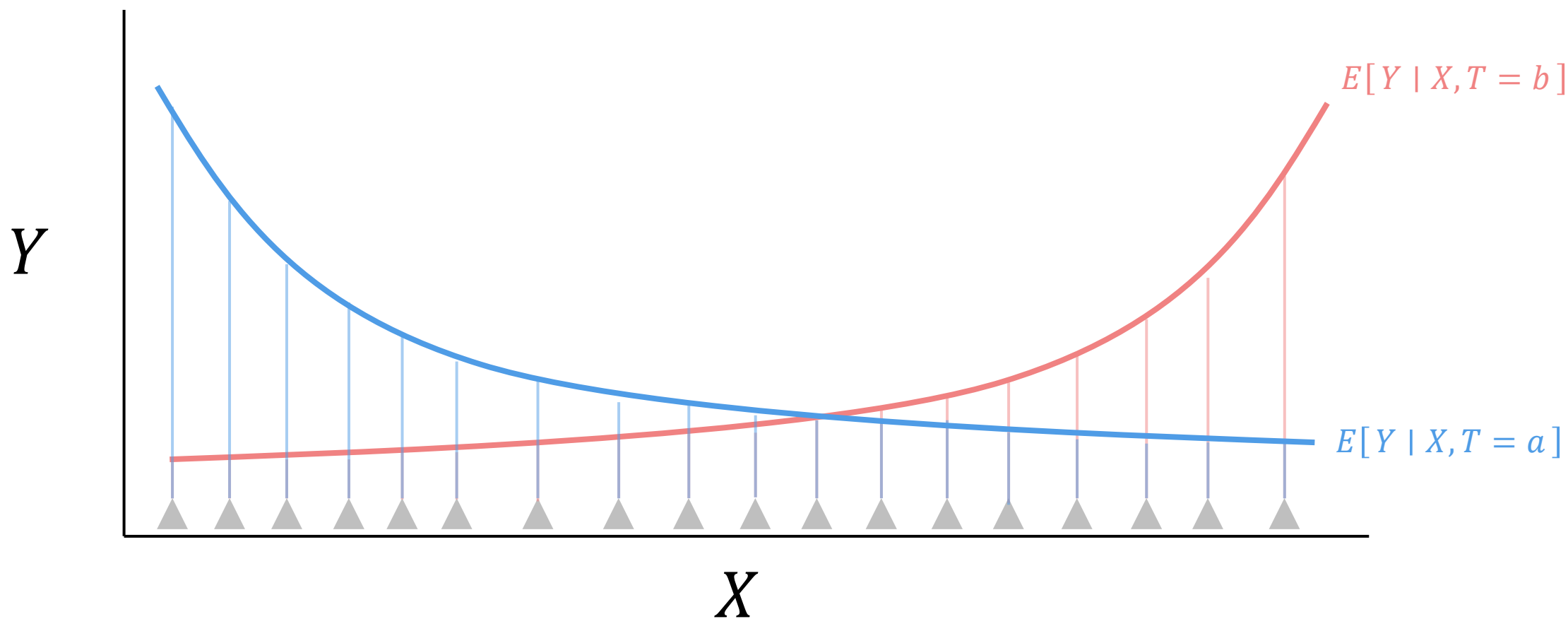


What is the Average Treatment Effect?



What is the Average Treatment Effect?

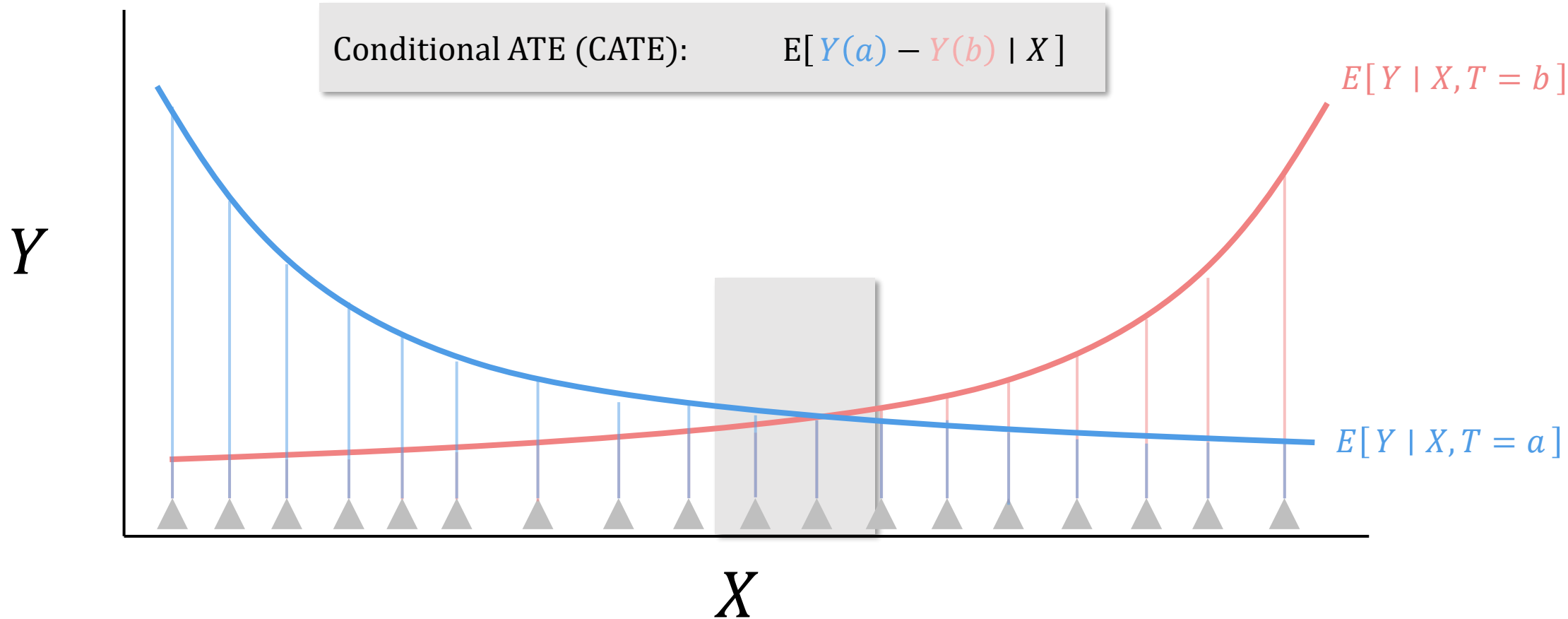
Average Treatment Effect (ATE): $E[Y(a) - Y(b)]$



What is the (Conditional) Average Treatment Effect?

Average Treatment Effect (ATE): $E[Y(a) - Y(b)]$

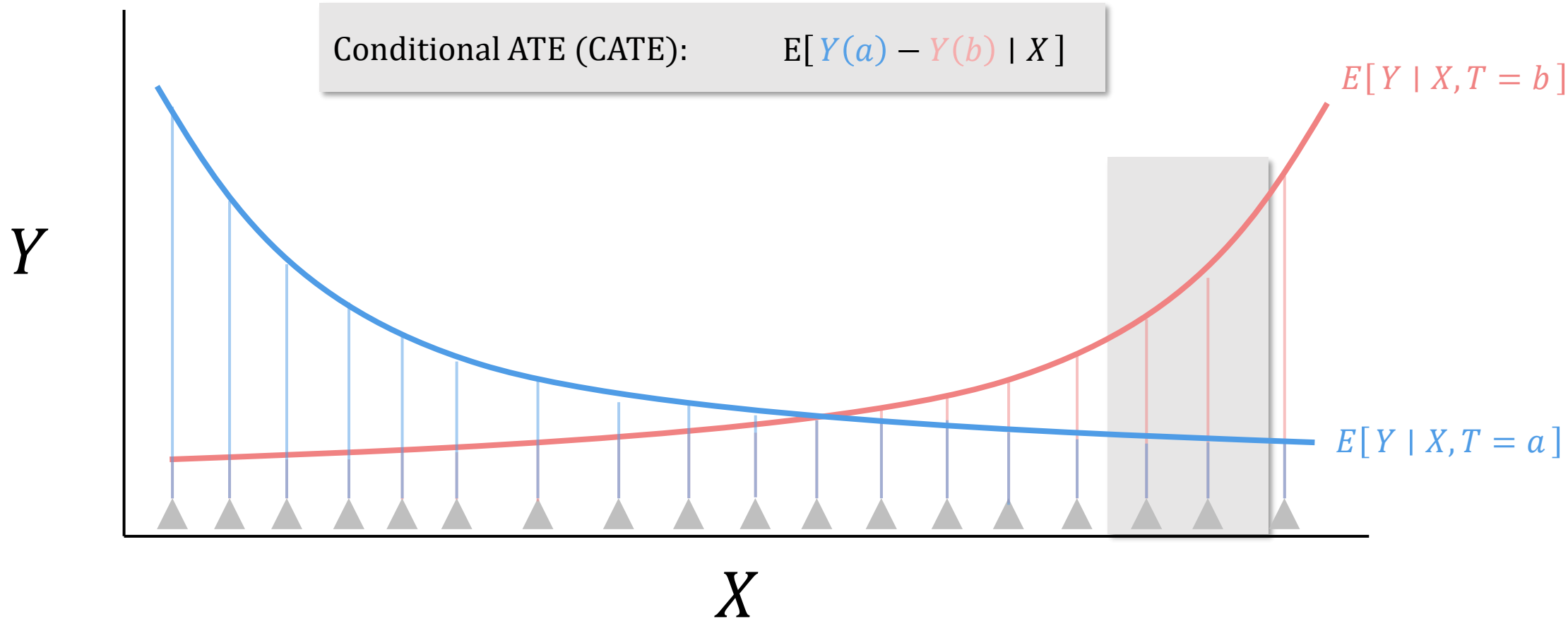
Conditional ATE (CATE): $E[Y(a) - Y(b) | X]$



What is the (Conditional) Average Treatment Effect?

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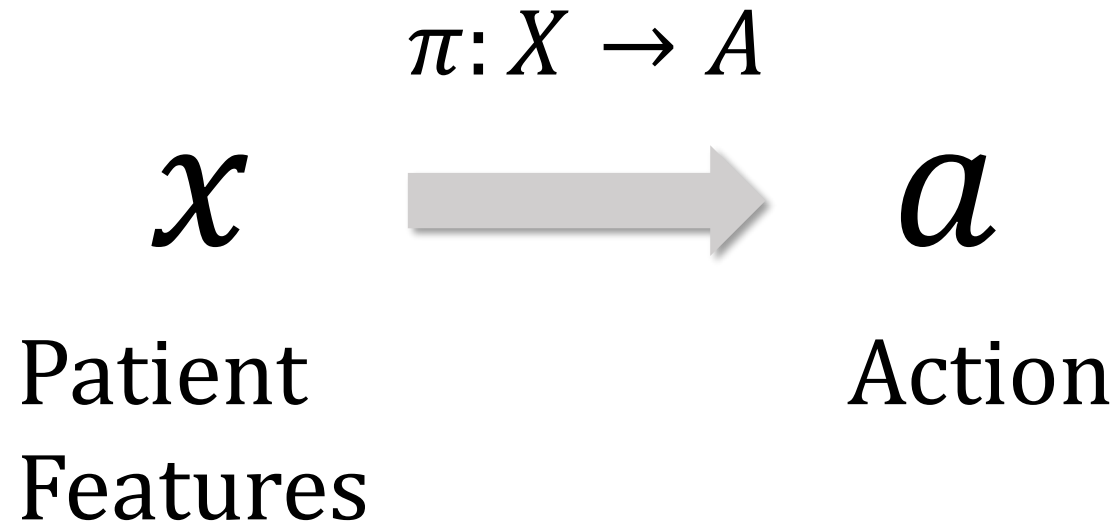
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Policy Evaluation

What is a policy?

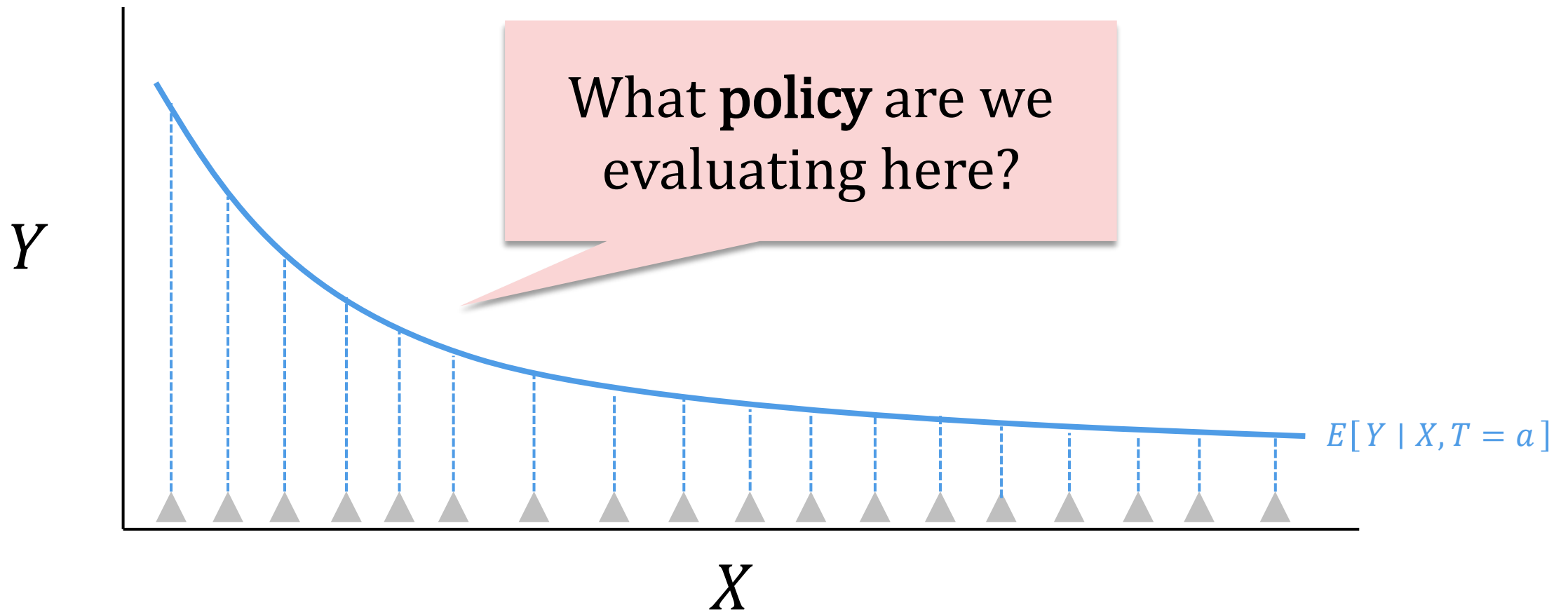
- A policy maps from **observed features** to **recommended actions**



(Or a distribution over actions)

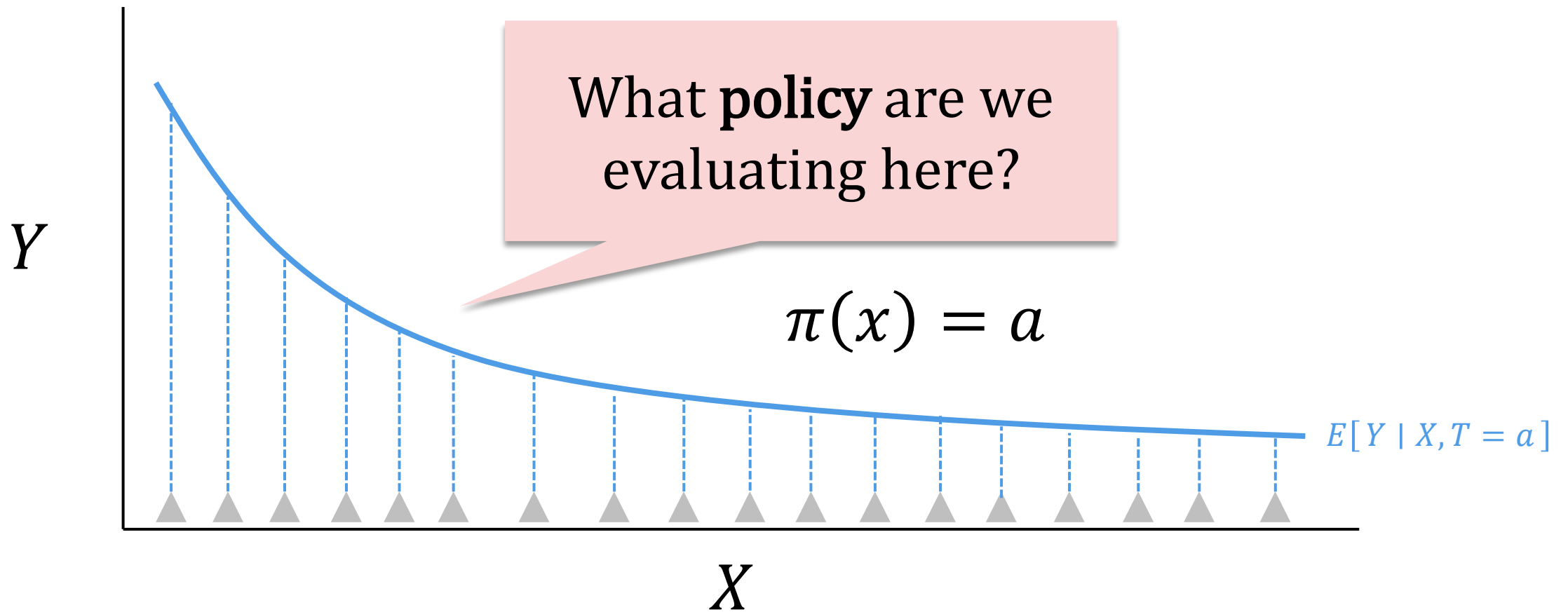
Causal Effects as Policy Evaluation

$$E[Y(a)] = E_x[E[Y \mid X, T = a]]$$



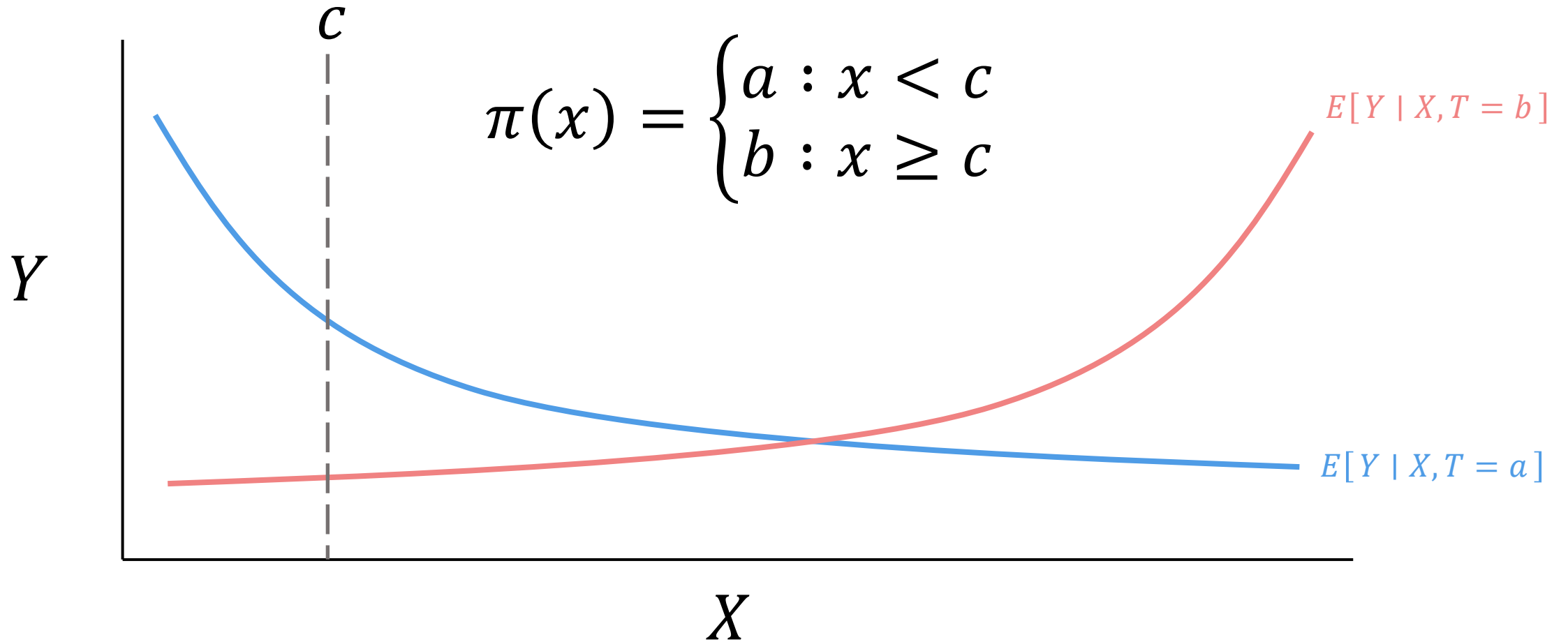
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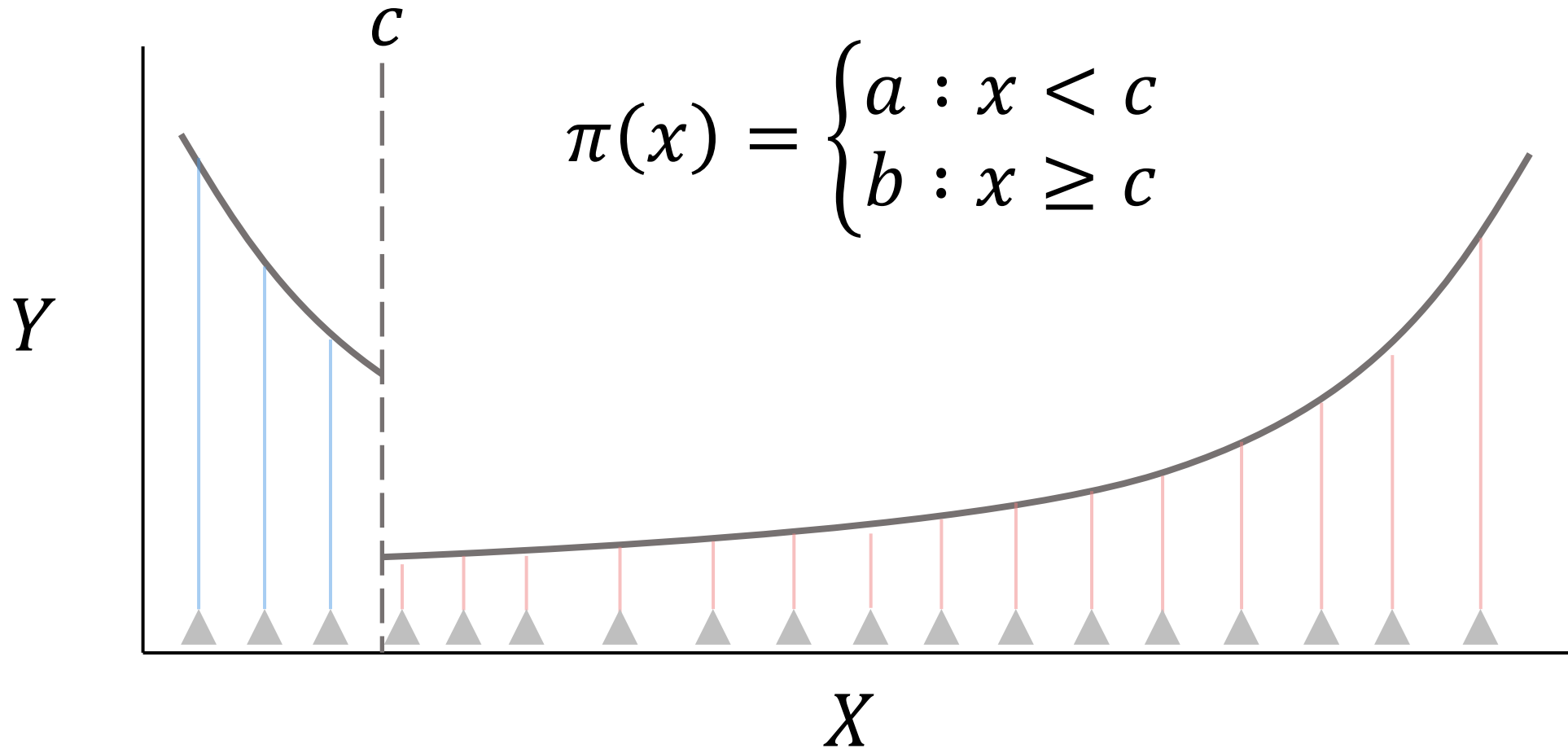
What is the value of a policy?

$$E[Y(\pi(x))] = E_x[E[Y | X, T = \pi(x)]]$$



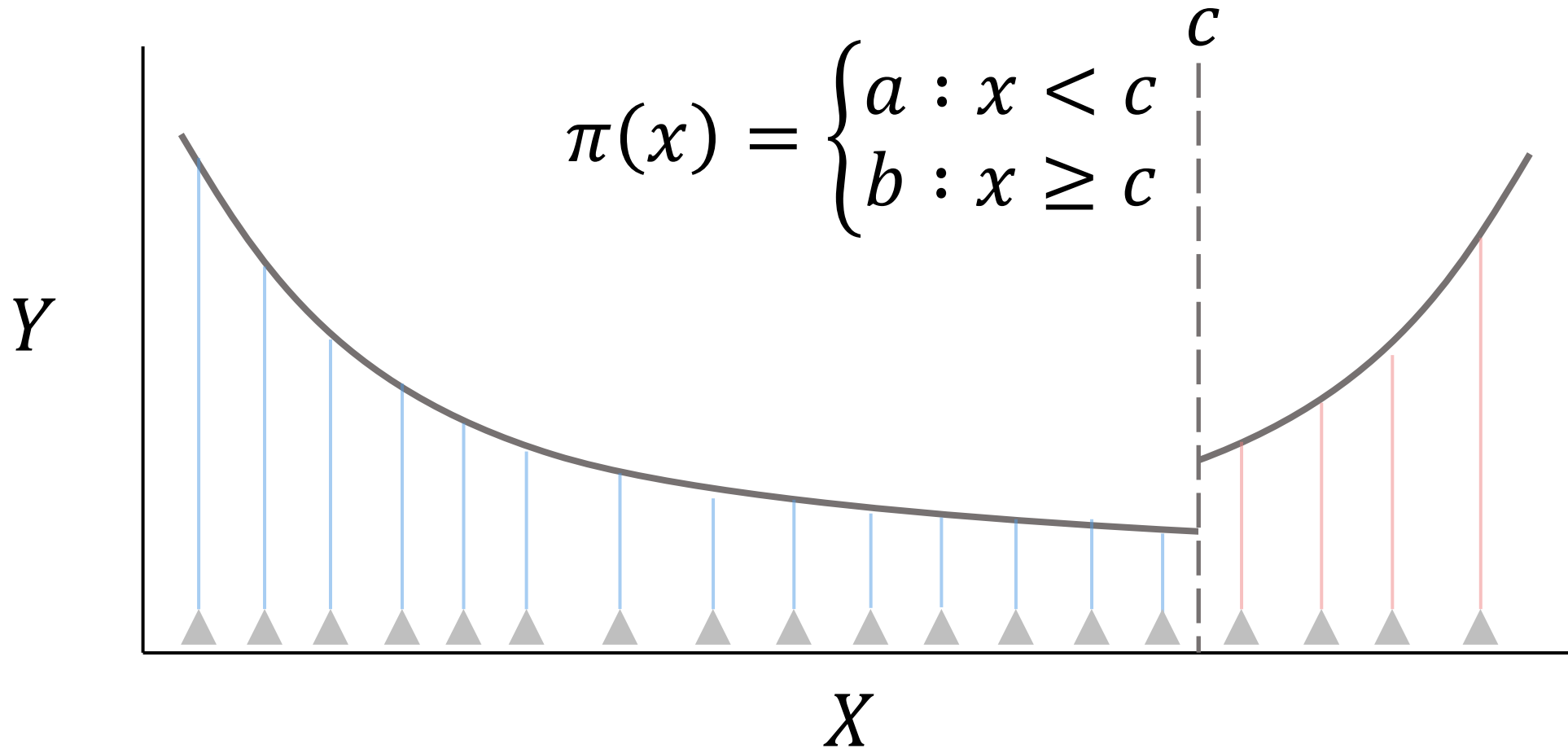
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What is the value of a policy?

$$E[Y(\pi(x))] = E_x[E[Y \mid X, T = \pi(x)]]$$



How do we evaluate a policy?

$$E[Y(\pi(x))] = E_x[E[Y \mid X, T = \pi(x)]]$$

1

Outcome Regression

$$\hat{E}[Y(\pi(x))] = \frac{1}{n} \sum_{i=1}^n f(x_i, \pi(x_i))$$

$$f(x, t) \approx E[Y \mid X = x, T = t]$$

How do we evaluate a policy?

$$E[Y(\pi(x))] = E_x[E[Y \mid X, T = \pi(x)]]$$

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2

Propensity Reweighting

$$\hat{E}[Y(\pi(x))] = \frac{1}{n} \sum_{i=1}^n \frac{1\{t_i = \pi(x_i)\}}{e(x_i, t_i)} Y_i \quad e(x, t) \approx p[T = t \mid X = x]$$

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3

“Doubly Robust”

$$\hat{E}[Y(\pi(x))] = \frac{1}{n} \sum_{i=1}^n \frac{1\{t_i = \pi(x_i)\}}{e(x_i, t_i)} (Y_i - f(x_i, \pi(x_i))) + f(x_i, \pi(x_i))$$

Which policies can we evaluate?

(alternatively: For what types of patients can we evaluate a fixed policy?)

Which policies can we evaluate?

1

Consistency

When treatment t is given, we observe $Y(t)$

2

No interference

Your outcome is not impacted by the treatments of others

3

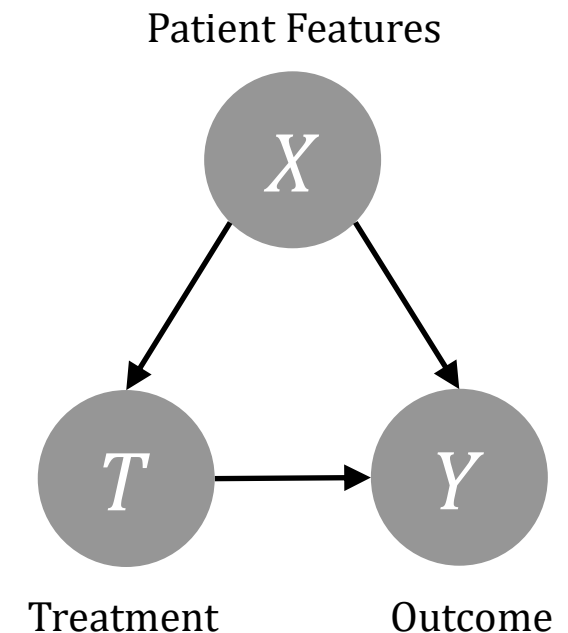
No unmeasured confounding

We have measured all relevant confounders

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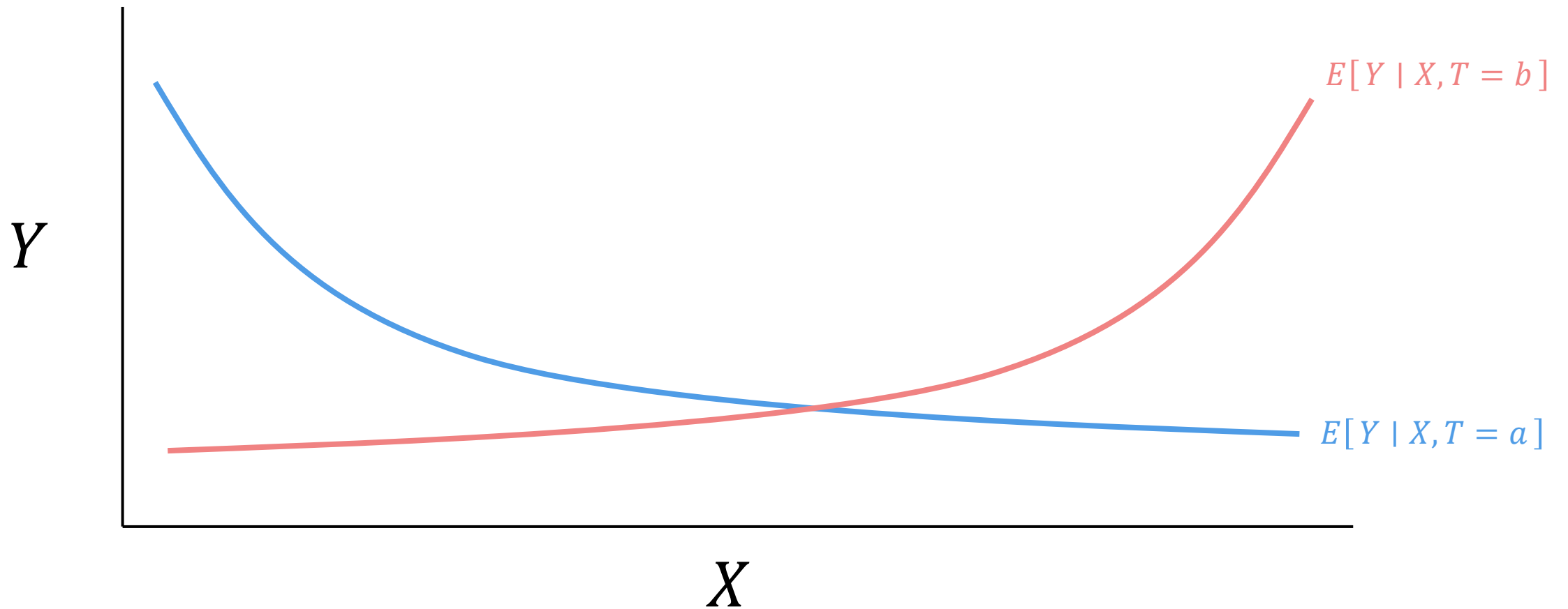
Overlap / Coverage

All types of patients receive all treatments*

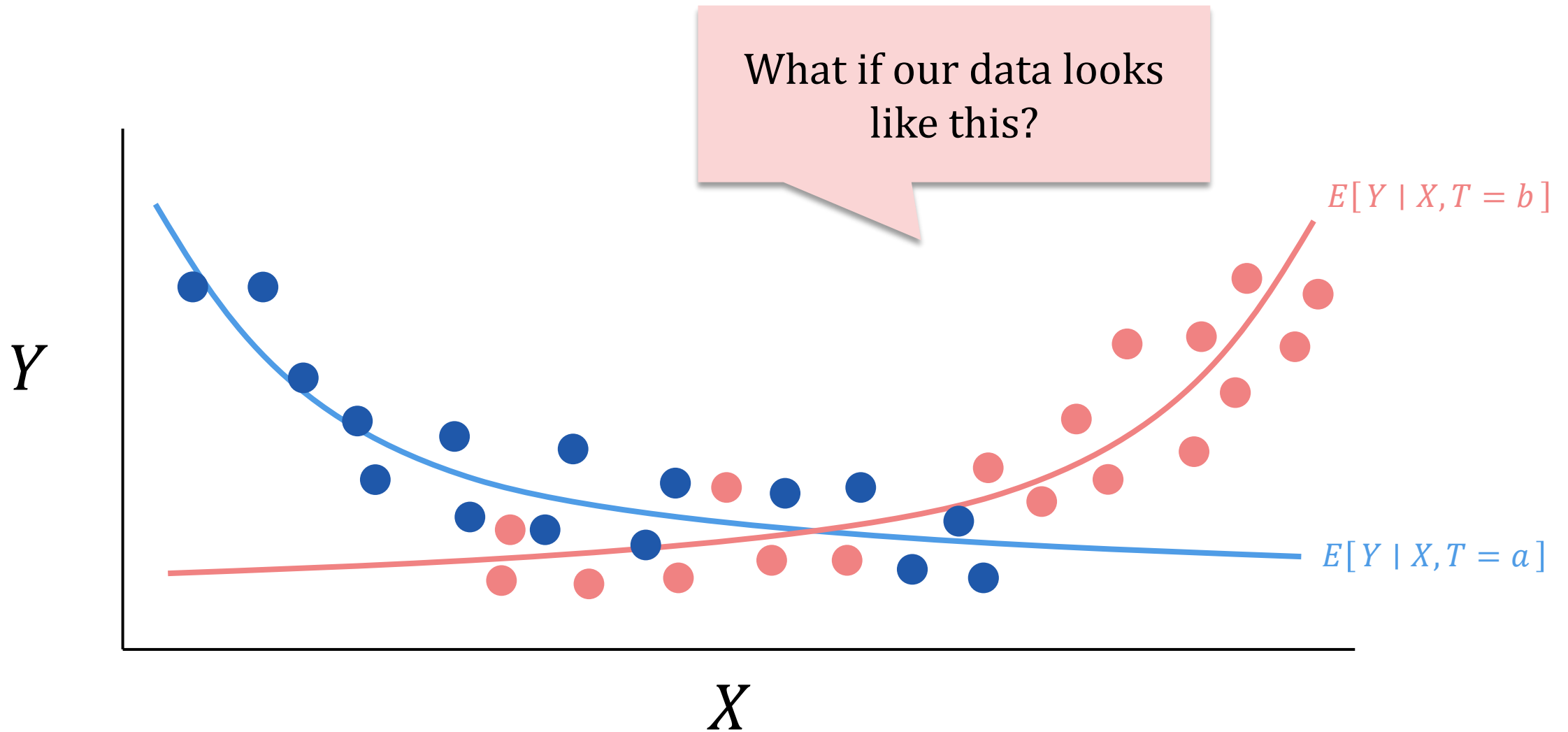


*More on this later, when we discuss policy evaluation

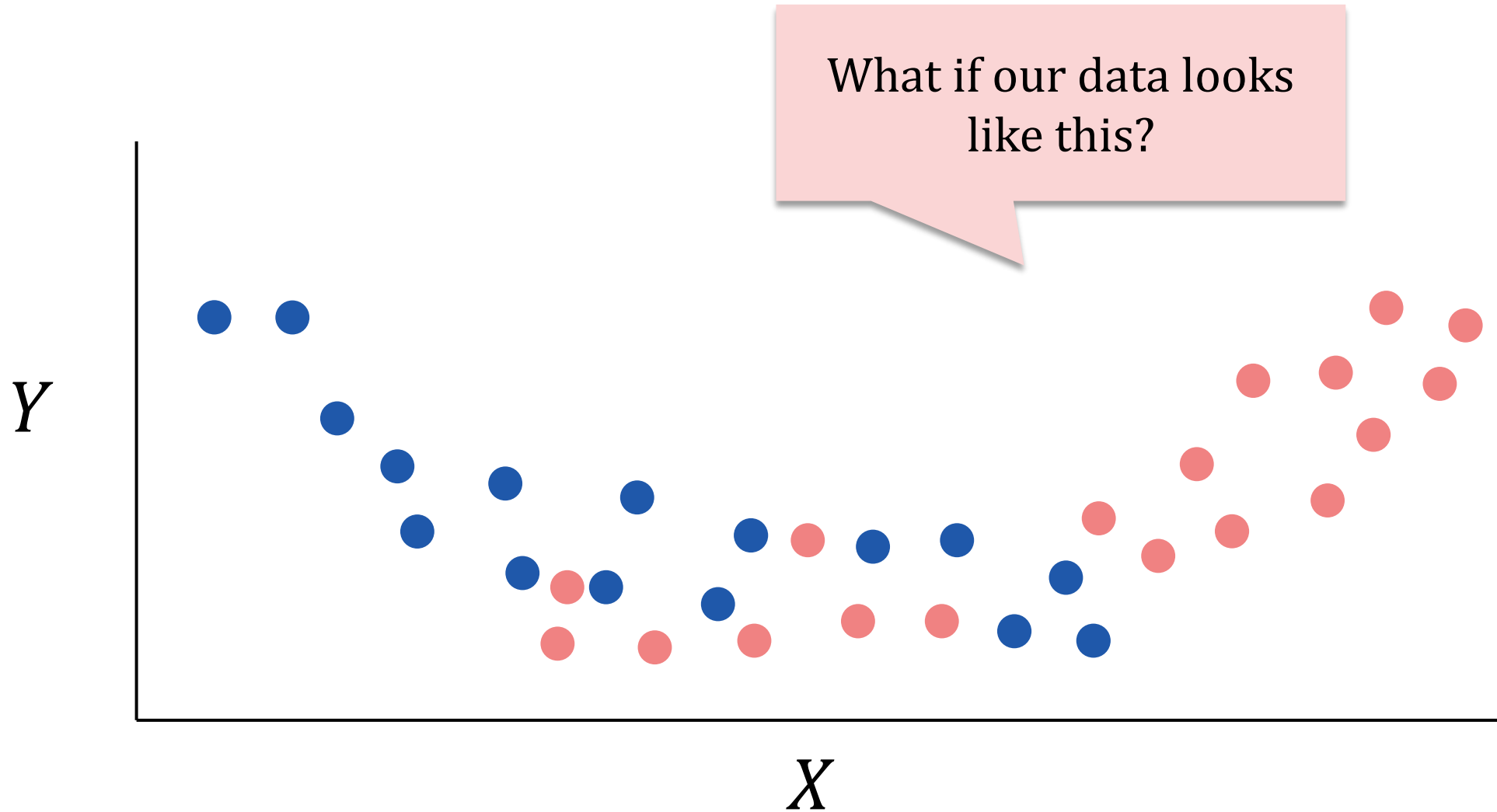
Which policies can we evaluate?



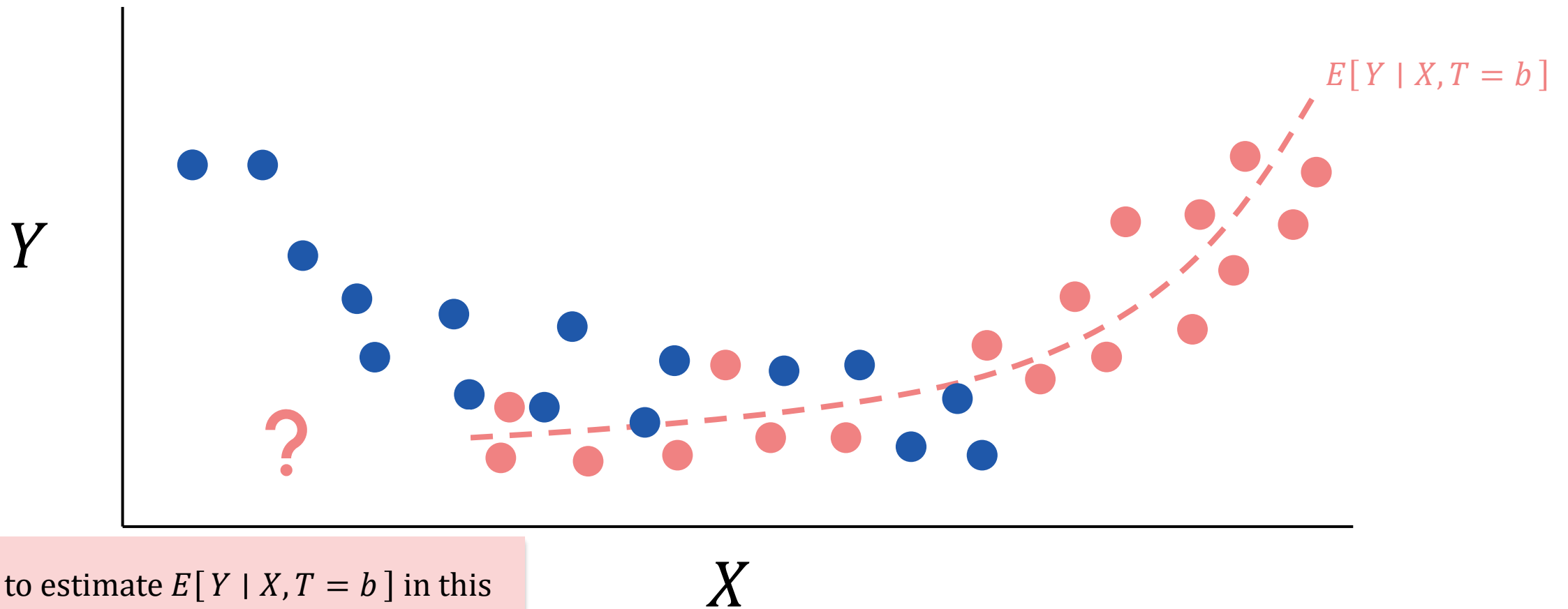
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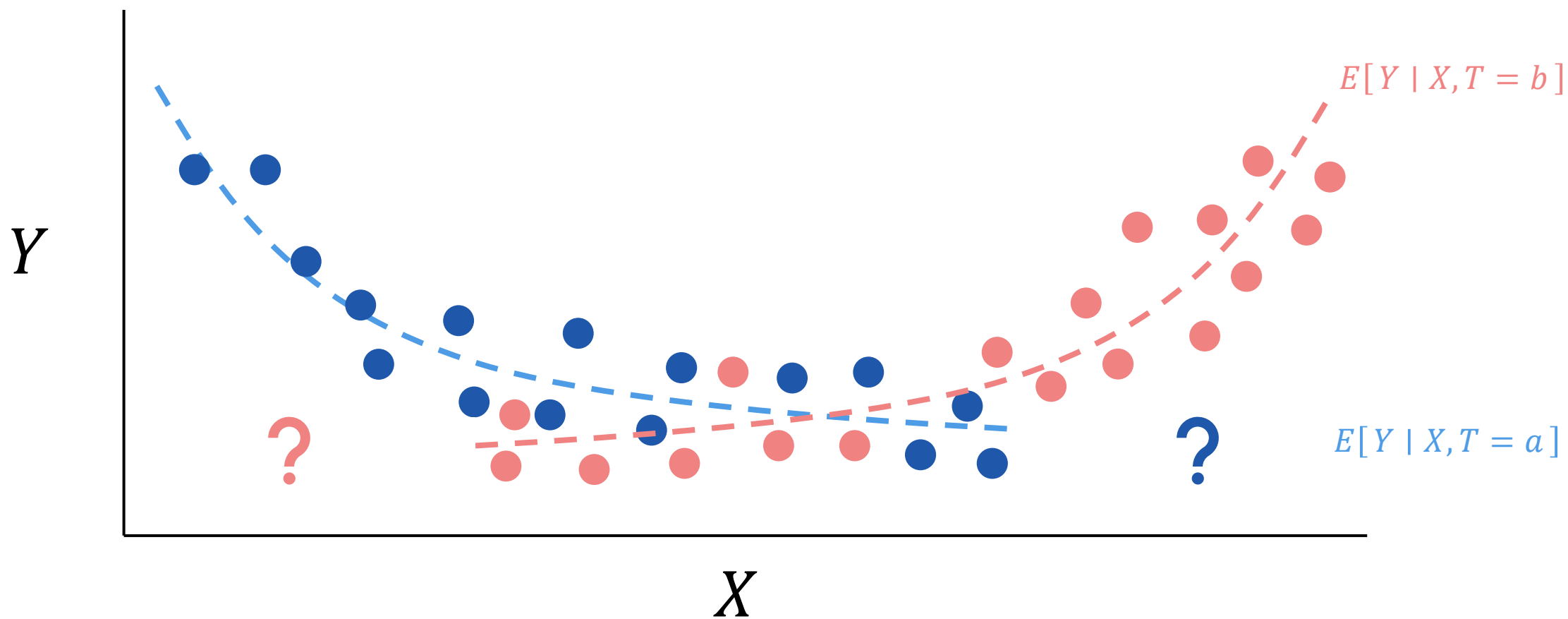


Which policies can we evaluate?



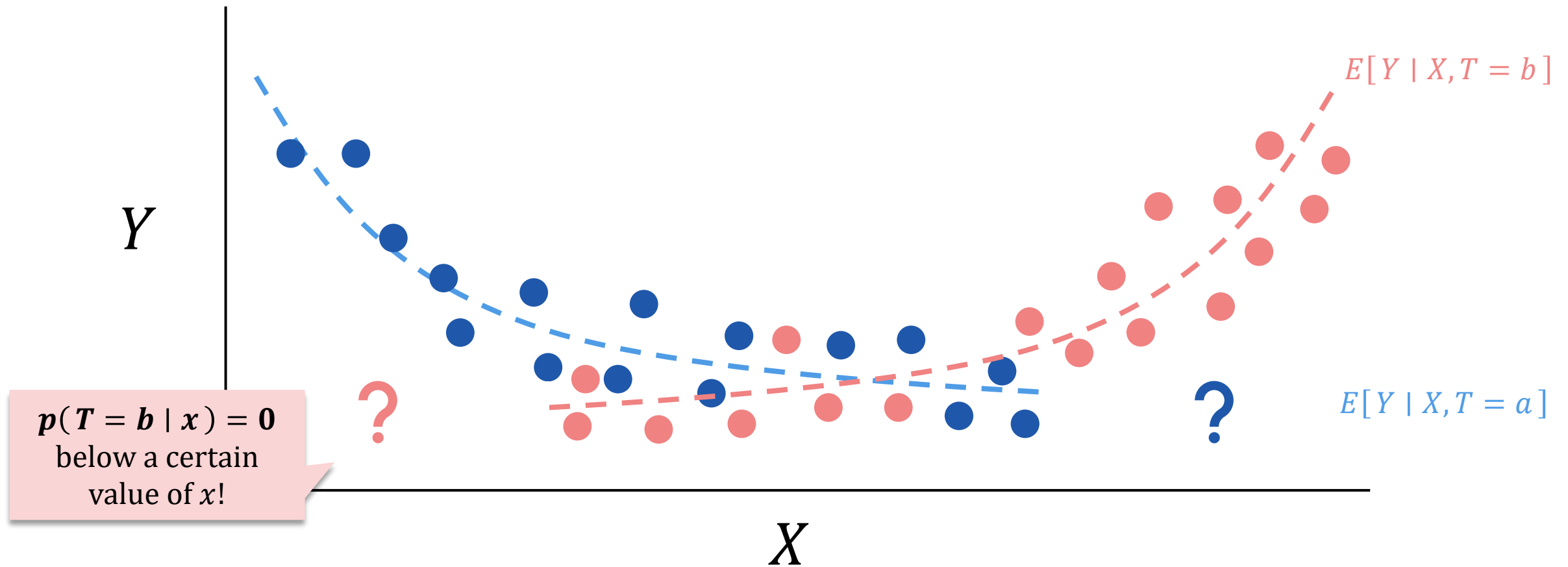
In order to estimate $E[Y | X, T = b]$ in this region, we will have to **extrapolate**

Which policies can we evaluate?



Which policies can we evaluate?

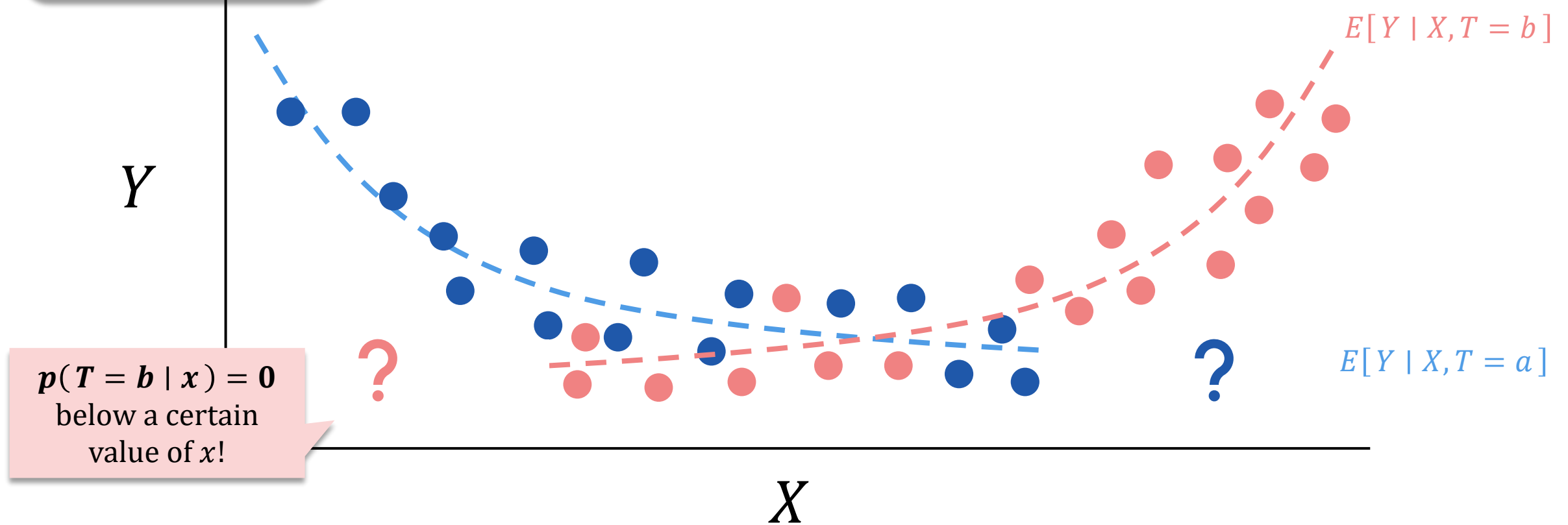
Coverage: For all x , $\pi(x) = t \longrightarrow p(t | x) > 0$



Which policies can we evaluate?

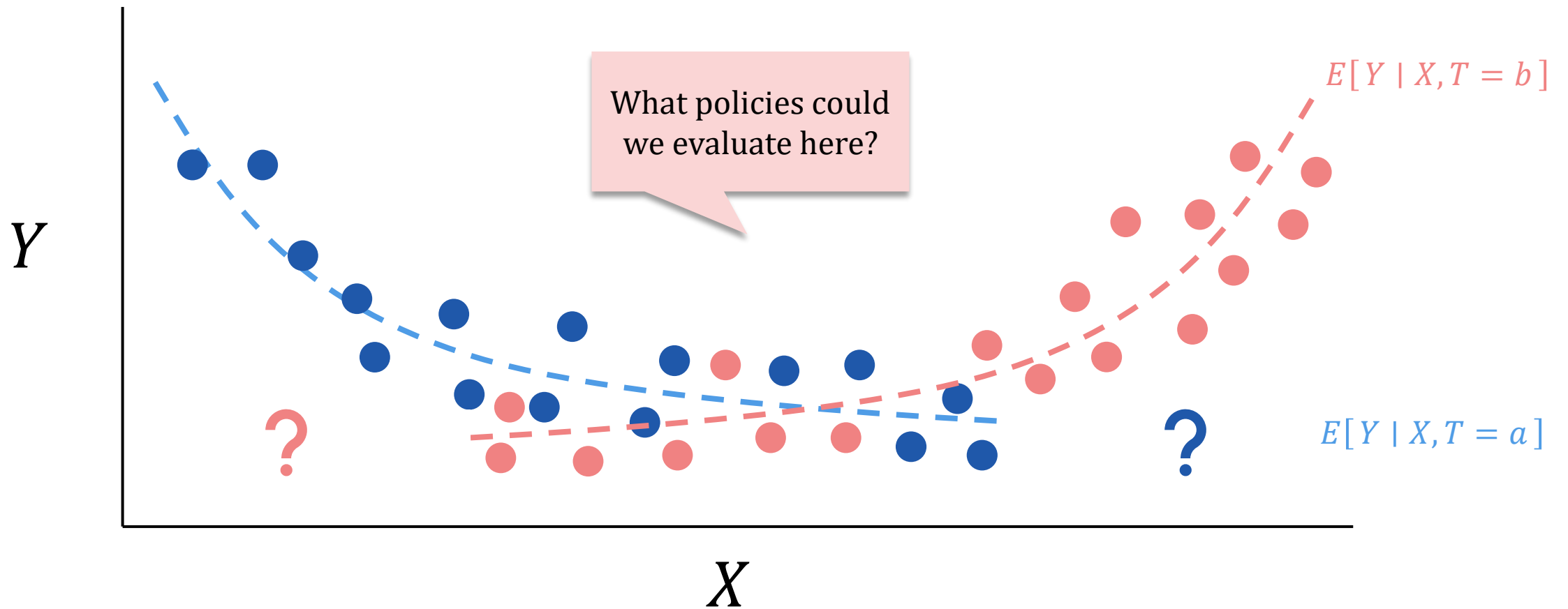
Depends on policy!
Does not need to
hold for all t

Coverage: For all x , $\pi(x) = t \implies p(t | x) > 0$



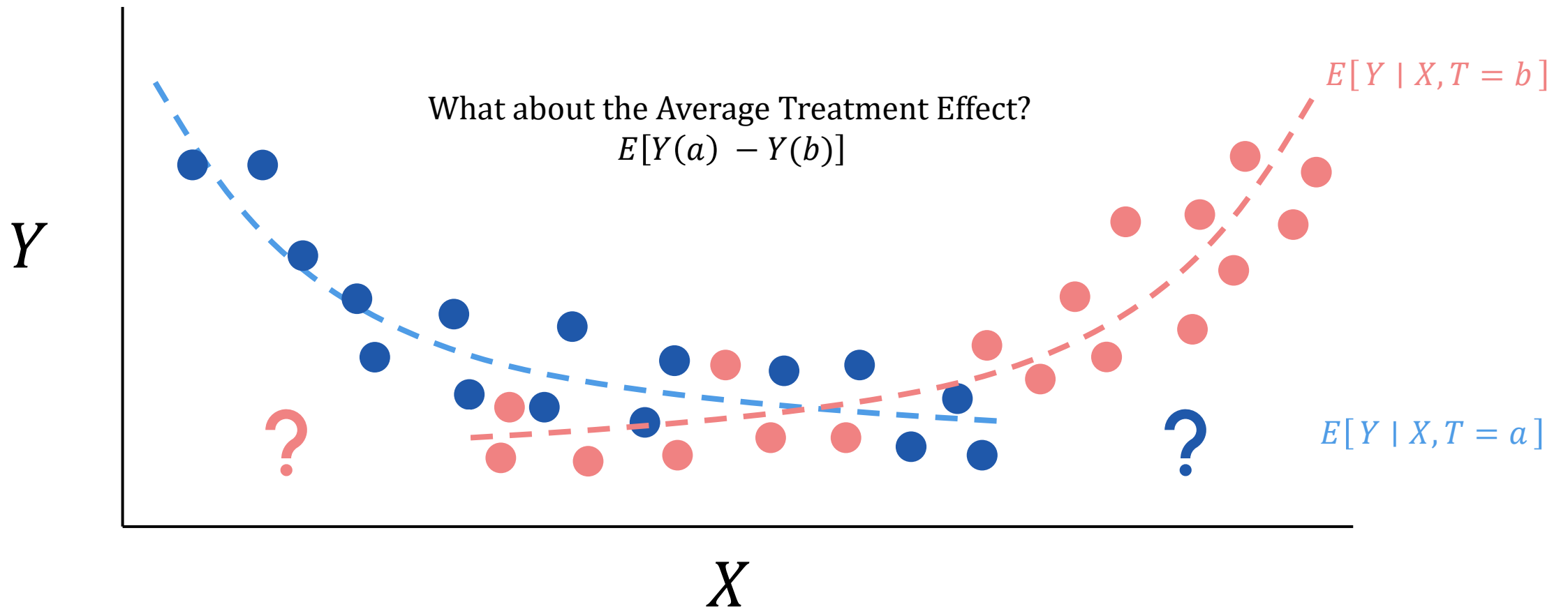
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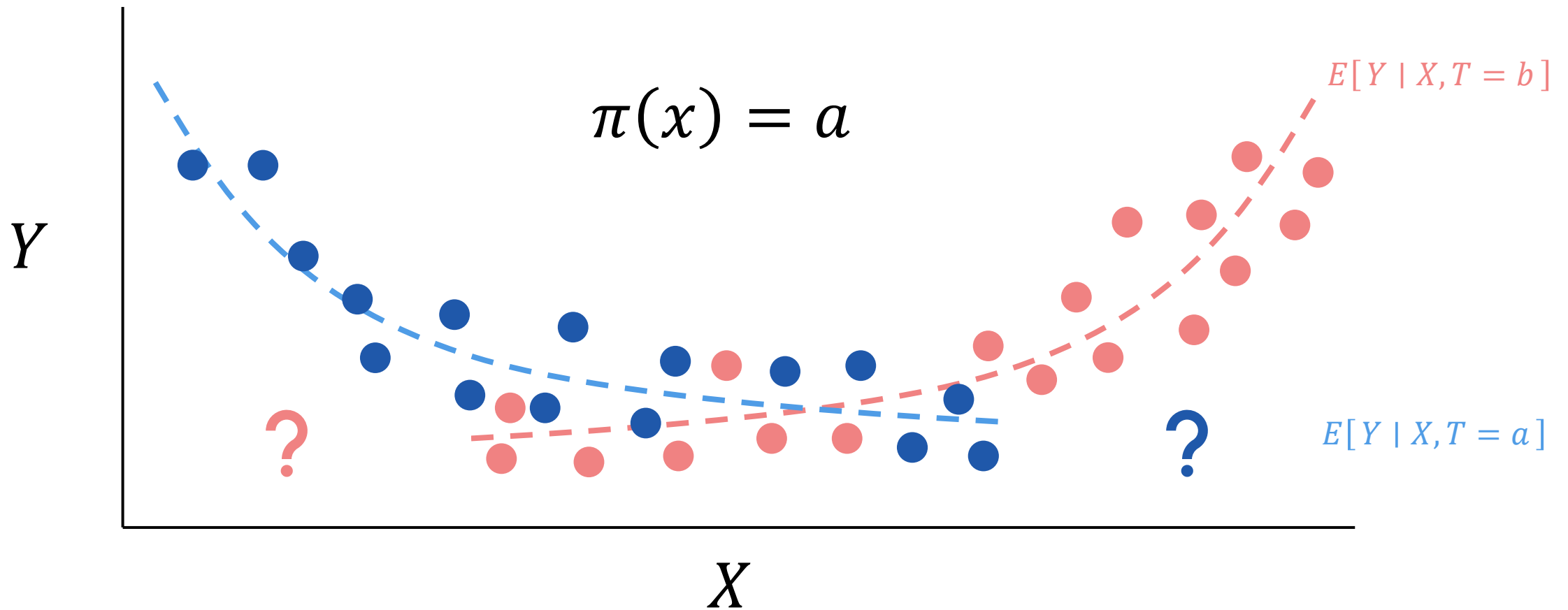
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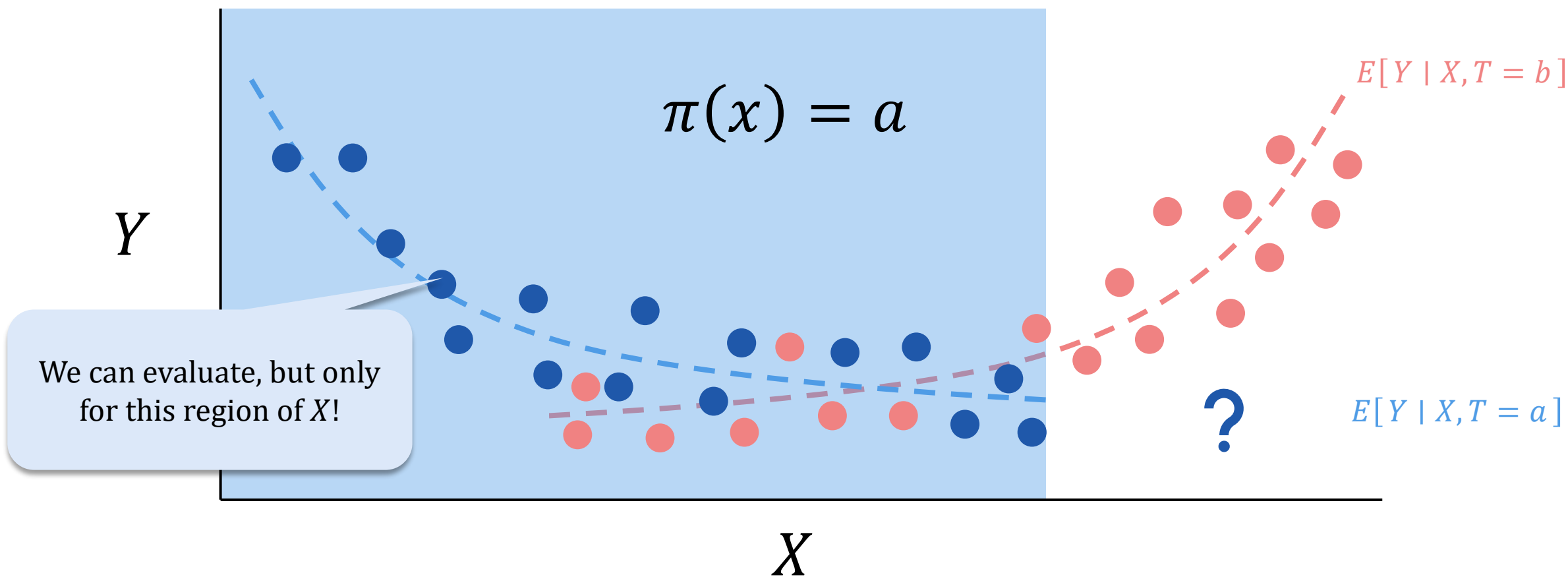
Where can we evaluate a fixed policy?

Coverage: For all x , $\pi(x) = t \longrightarrow p(t | x) > 0$



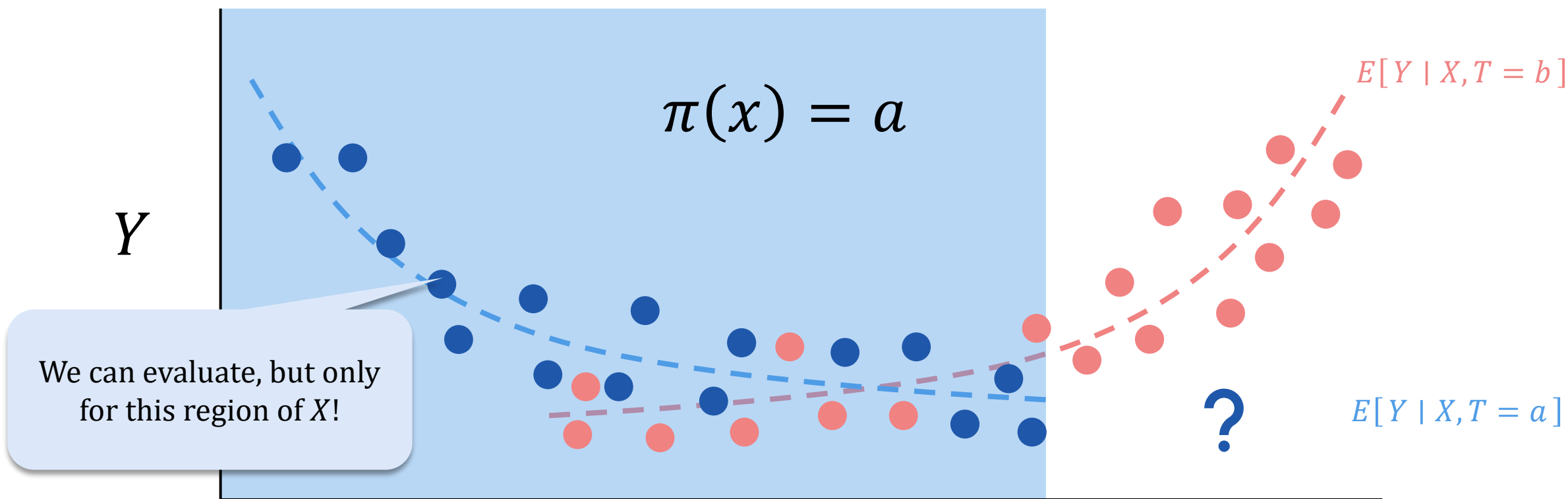
Where can we evaluate a fixed policy?

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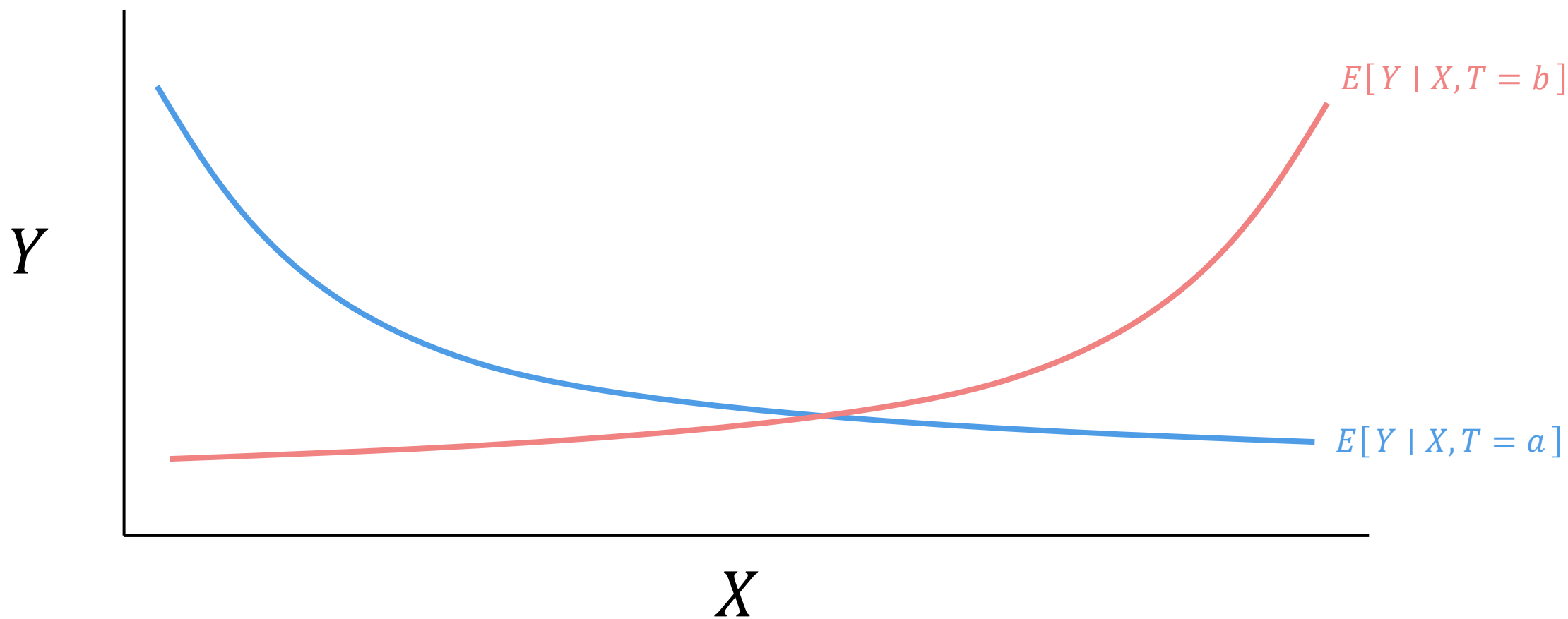
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Learning Policies from Data

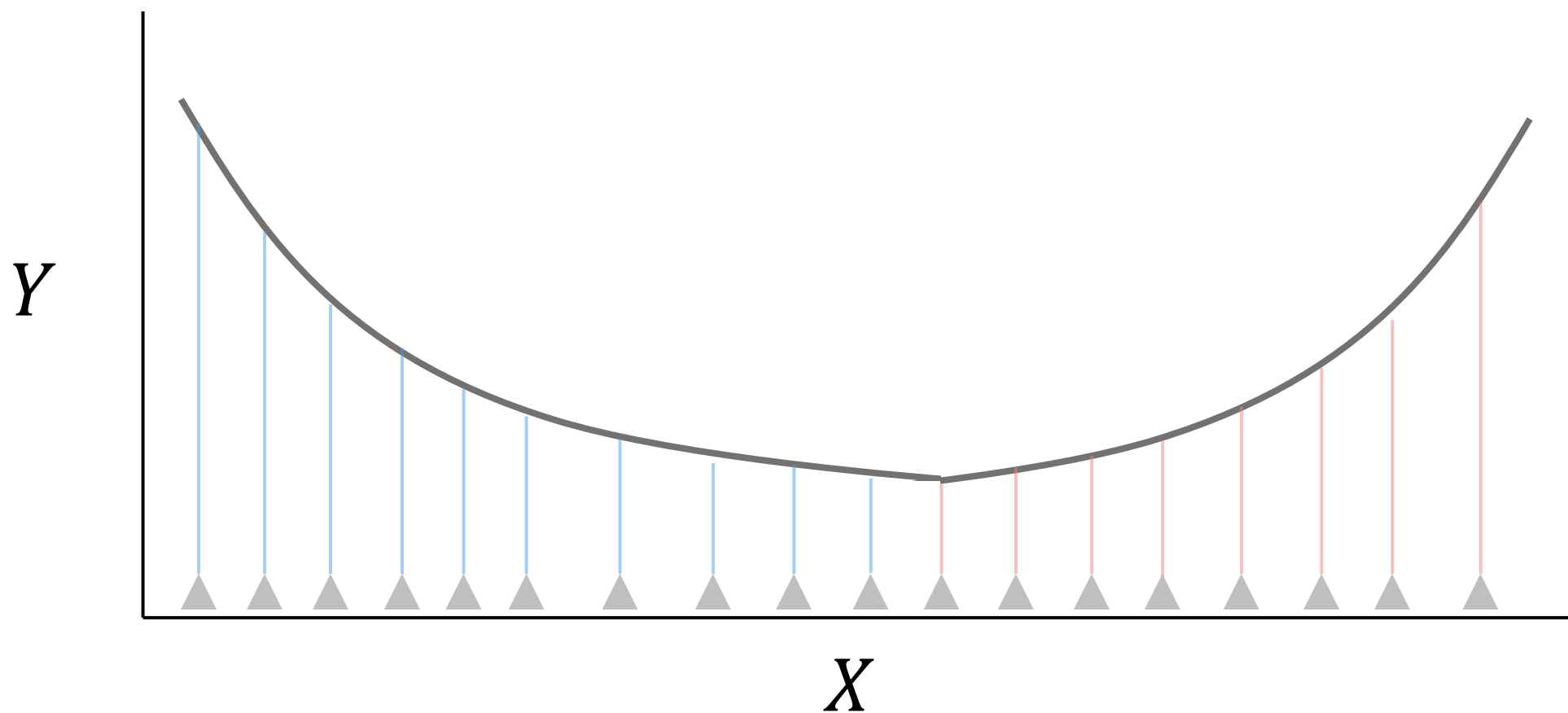
What is the optimal policy?

$$E[Y(\pi(x))] = E_x[E[Y | X, T = \pi(x)]]$$



What is the optimal policy?

$$E[Y(\pi(x))] = E_x[E[Y \mid X, T = \pi(x)]]$$



How to find the optimal policy?

Option #1: Estimate outcomes for each action, choose the best one!

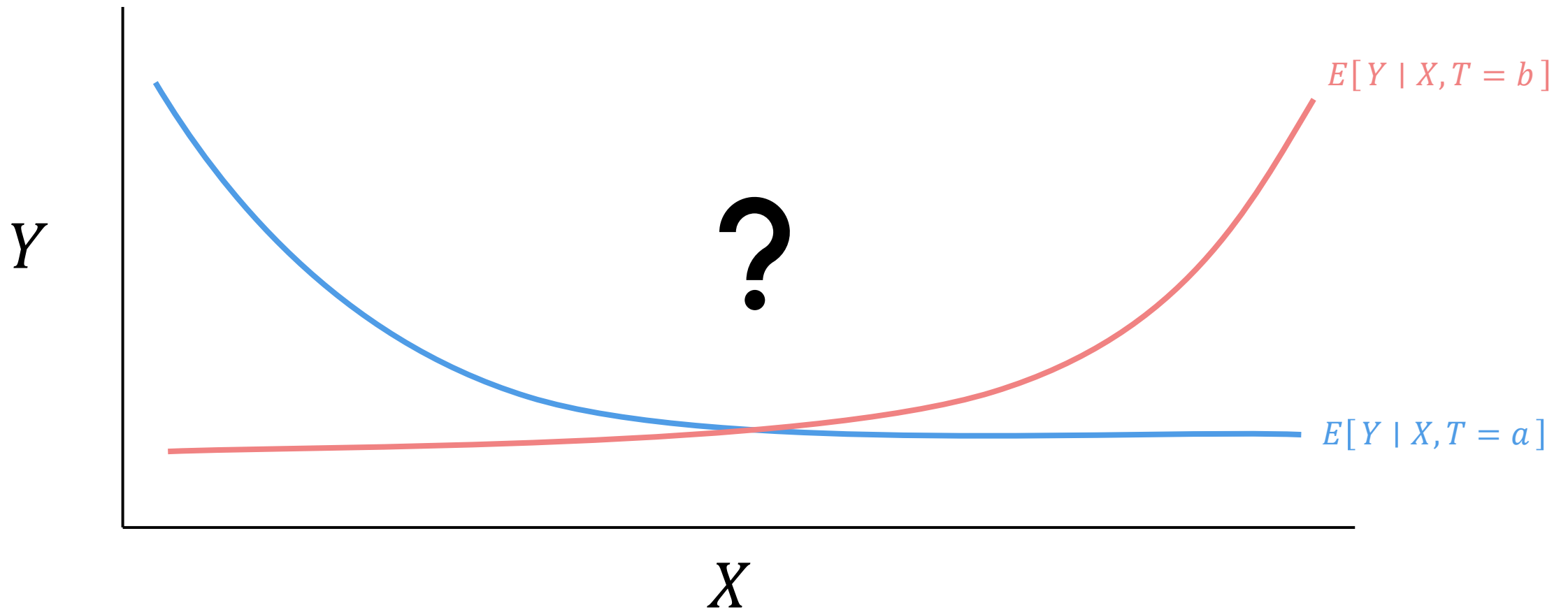
$$\pi(x) := \operatorname{argmax}_{t \in T} f(x, t)$$

- “Indirect” method
- Requires that regression function be “correct”
- The resulting policy could also be quite complex

$$f(x, t) \approx E[Y \mid X = x, T = t]$$



Indirect method may yield complex policies

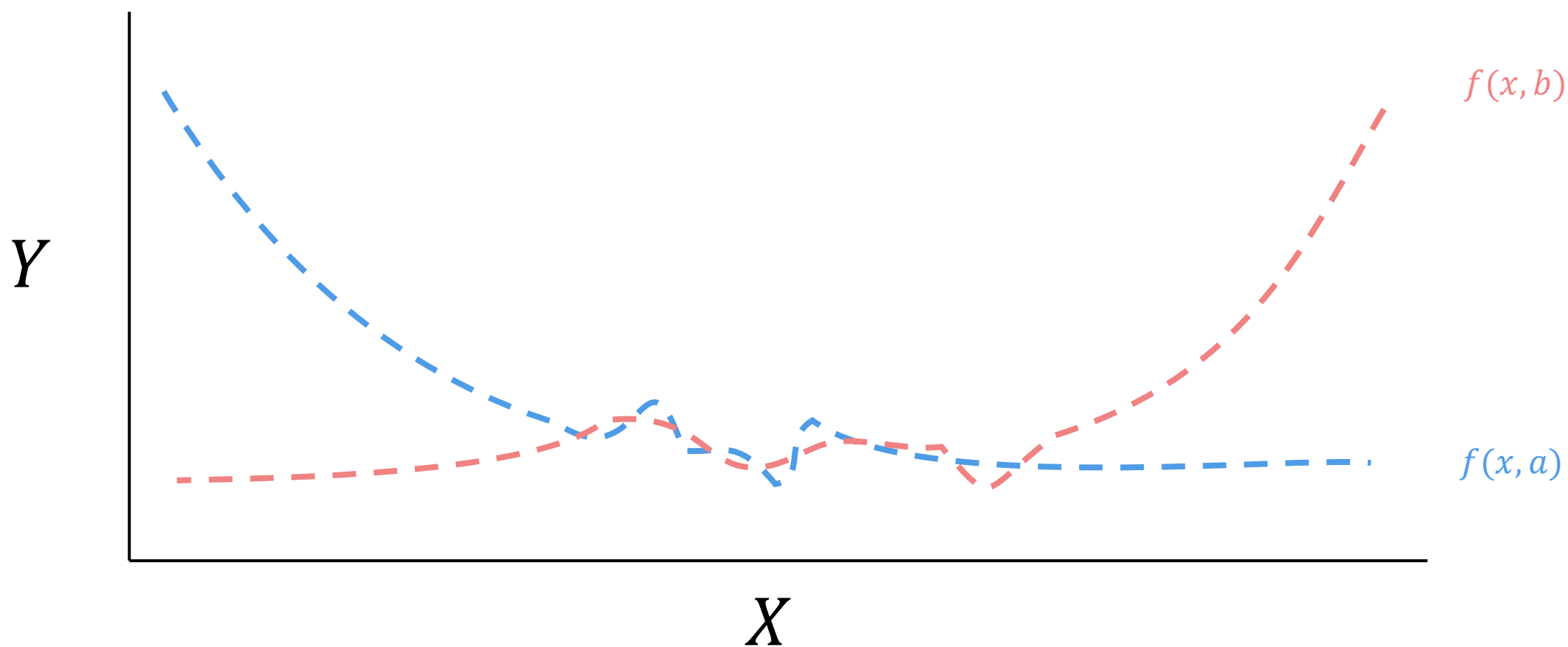
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Indirect method may yield complex policies



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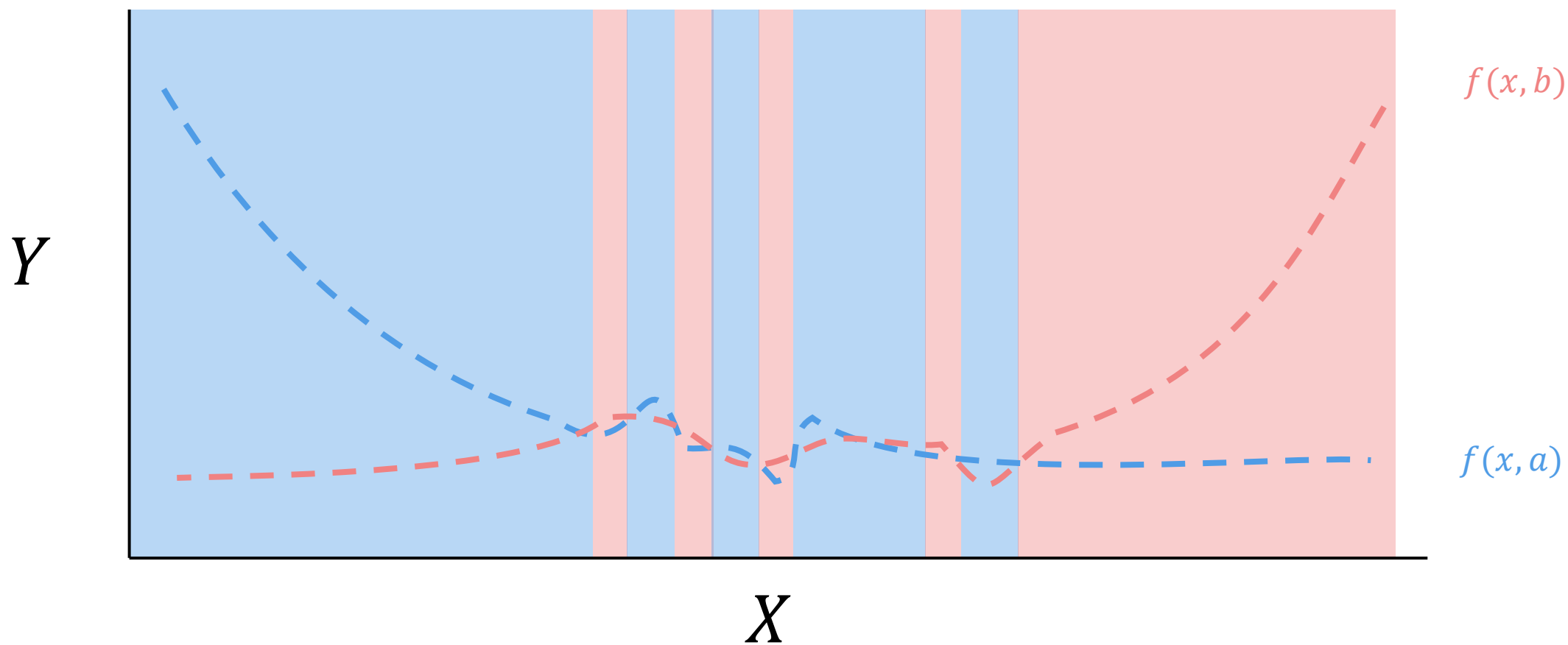
 $\pi(x) = a$
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Indirect method may yield complex policies

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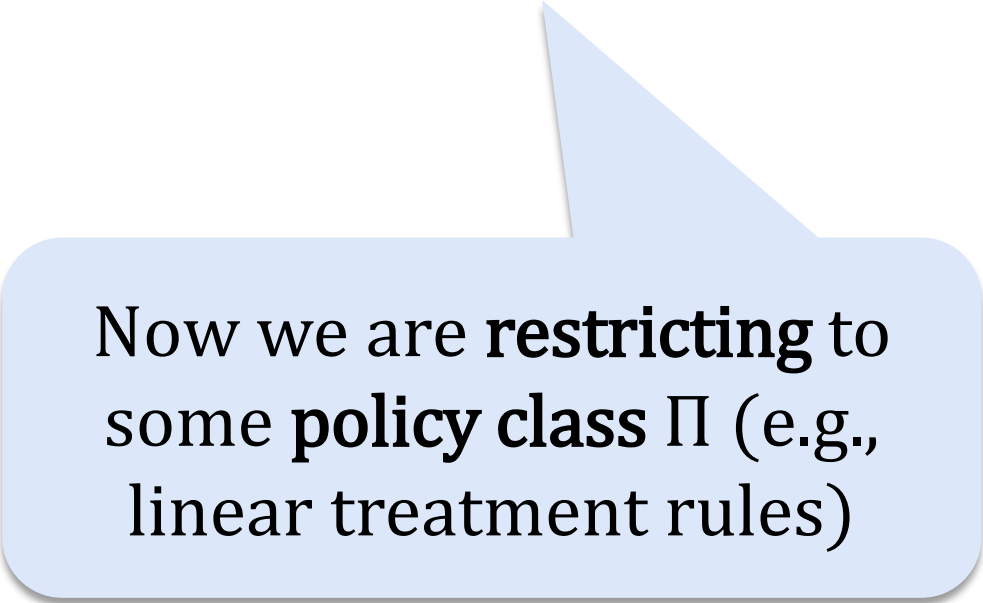
 $\pi(x) = a$
 $\pi(x) = b$



How to find the optimal policy?

Option #2: Directly solve for the best policy in a certain class

$$\pi^* = \operatorname{argmax}_{\pi \in \Pi} \hat{E}[Y(\pi(x))]$$



Now we are **restricting** to some **policy class** Π (e.g., linear treatment rules)

How to find the optimal policy?

Option #2 (“Direct”): Solve for the best policy in a certain class

$$\pi^* = \operatorname{argmax}_{\pi \in \Pi} \frac{1}{n} \sum_{i=1}^n \sum_{a \in A} 1\{\pi(x_i) = a\} * \widehat{W}_a(i)$$

Now we are **restricting** to some **policy class** Π (e.g., linear treatment rules)

“Doubly Robust” Estimator

$$\widehat{W}_a(i) := \frac{1\{t_i = a\}}{e(x_i, t_i)} (Y_i - f(x_i, a) + f(x_i, a))$$

Directly optimizing a policy

Option #2 (“Direct”): Solve for the best policy in a certain class

$$\pi^* = \operatorname{argmax}_{\pi \in \Pi} \frac{1}{n} \sum_{i=1}^n \sum_{a \in A} 1\{\pi(x_i) = a\} * \hat{W}_a(i)$$

- We can optimize over simple (interpretable) policies, even if outcome / propensity models are very flexible and complex
- Conceptually straightforward to add other actions (e.g., deferral)

Not obvious how to optimize this! Why?

Policy Optimization as classification

$$\pi^* = \operatorname{argmax}_{\pi \in \Pi} \frac{1}{n} \sum_{i=1}^n \sum_{a \in A} 1\{\pi(x_i) = a\} * \hat{W}_a(i)$$

Difficult optimization problem! Analogous to weighted 0-1 loss in classification.

Policy Optimization as classification

$$\pi^* = \operatorname{argmax}_{\pi \in \Pi} \frac{1}{n} \sum_{i=1}^n \sum_{a \in A} 1\{\pi(x_i) = a\} * \hat{W}_a(i)$$

Use convex surrogate for indicator function

Convert to minimization

Redefine weights (e.g., ensure nonnegative) so that reformulated problem remains convex

Goal: Reformulate optimization problem so that

- It is easier to optimize
- It has the same optimal solution

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Recommended Reading (Policy Learning)

- [1] Y. Q. Zhao, E. B. Laber, Y. Ning, S. Saha, and B. E. Sands, **Efficient augmentation and relaxation learning for individualized treatment rules using observational data**, J. Mach. Learn. Res., vol. 20, pp. 1–23, 2019.
- [2] X. Huang, Y. Goldberg, and J. Xu, **Multicategory individualized treatment regime using outcome weighted learning**, Biometrics, August 2018, pp. 1216–1227, 2019.
- [3] S. Athey and S. Wager, **Policy Learning with Observational Data**, Econometrica (Forthcoming), 2020.
- [4] N. Kallus, **More Efficient Policy Learning via Optimal Retargeting**, J. Am. Stat. Assoc., 2020.

Disclaimer: Selected set of (very) recent papers, but good place to find references to broader literature